

NATIONAL INSTRUMENTS

LabVIEW



Simulation in LabVIEW

Hans-Petter Halvorsen, M.Sc.

Software

- LabVIEW
- LabVIEW Control Design and Simulation Module
 - This module is used for creating Control and Simulation applications with LabVIEW.
 - Here you will find PID controllers, etc. The module is available as a palette on your block diagram.

All LabVIEW Software can be downloaded here: www.ni.com/download

Contents

- Block Diagram Simulation based on differential Equations
 - Using the Simulation Loop
- PID Control with built-in PID blocks/functions
- Creating and using Simulation Subsystems
- Simulations using a While Loop with Subsystems inside



What is LabVIEW?

Hans-Petter Halvorsen, M.Sc.

LabVIEW = Fun!

Graphical Programming:

- Very different from traditional programming like VB, C#, Maple, MATLAB, MathScript, etc.
- It is more like a “drawing program” than a Programming Language
- This makes it easy to use for those who are not programmers (or dont like programming 😊)
- Excellent tool when using Hardware, when you need to take Measurements (DAQ), etc.
- It is fun and makes you very creative!

LabVIEW Example

LabVIEW has the same things as other programming languages, but in a graphical way!

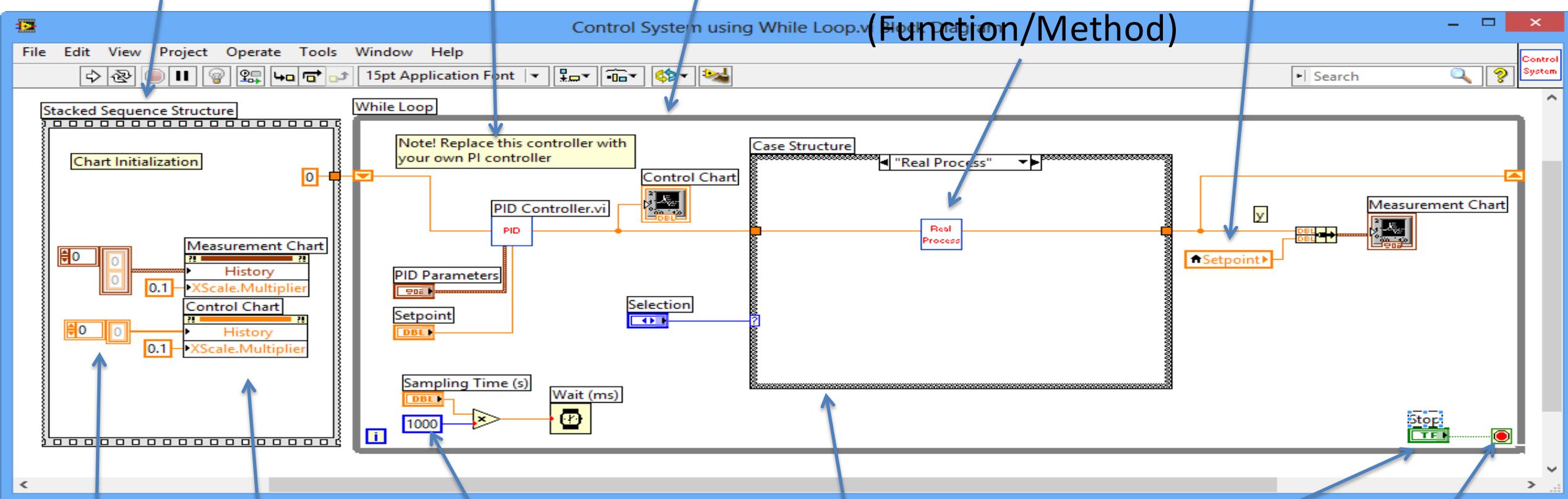
Sequence Structure

Comment

While Loop

Sub VI

Local Variable



(Function/Method)

Property Nodes

Constants

Case Structure Stop Button
(if-else)

Condition

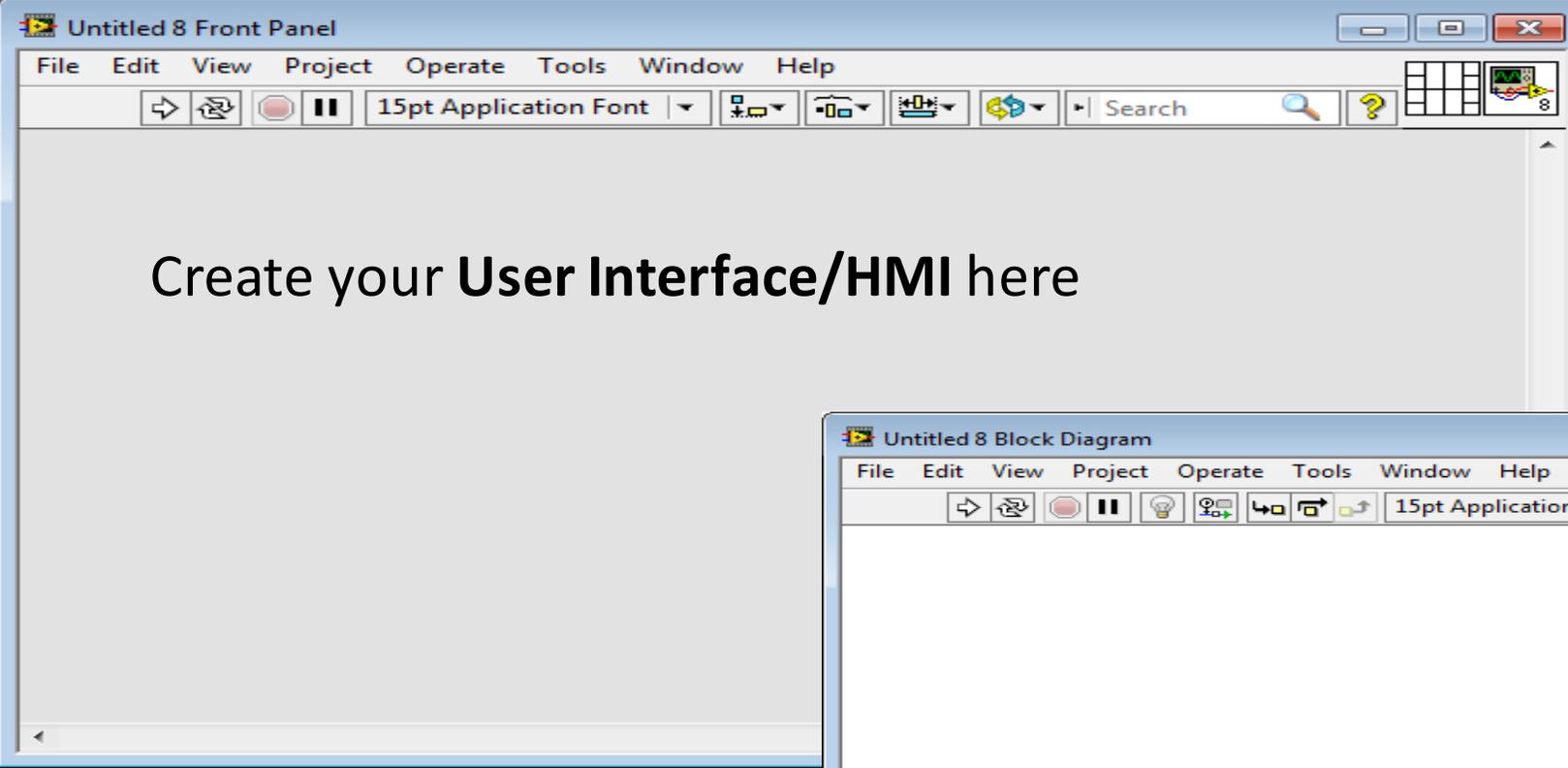
Arrays

Note! To do something with an object – Right-click on it (When shall the loop end?)

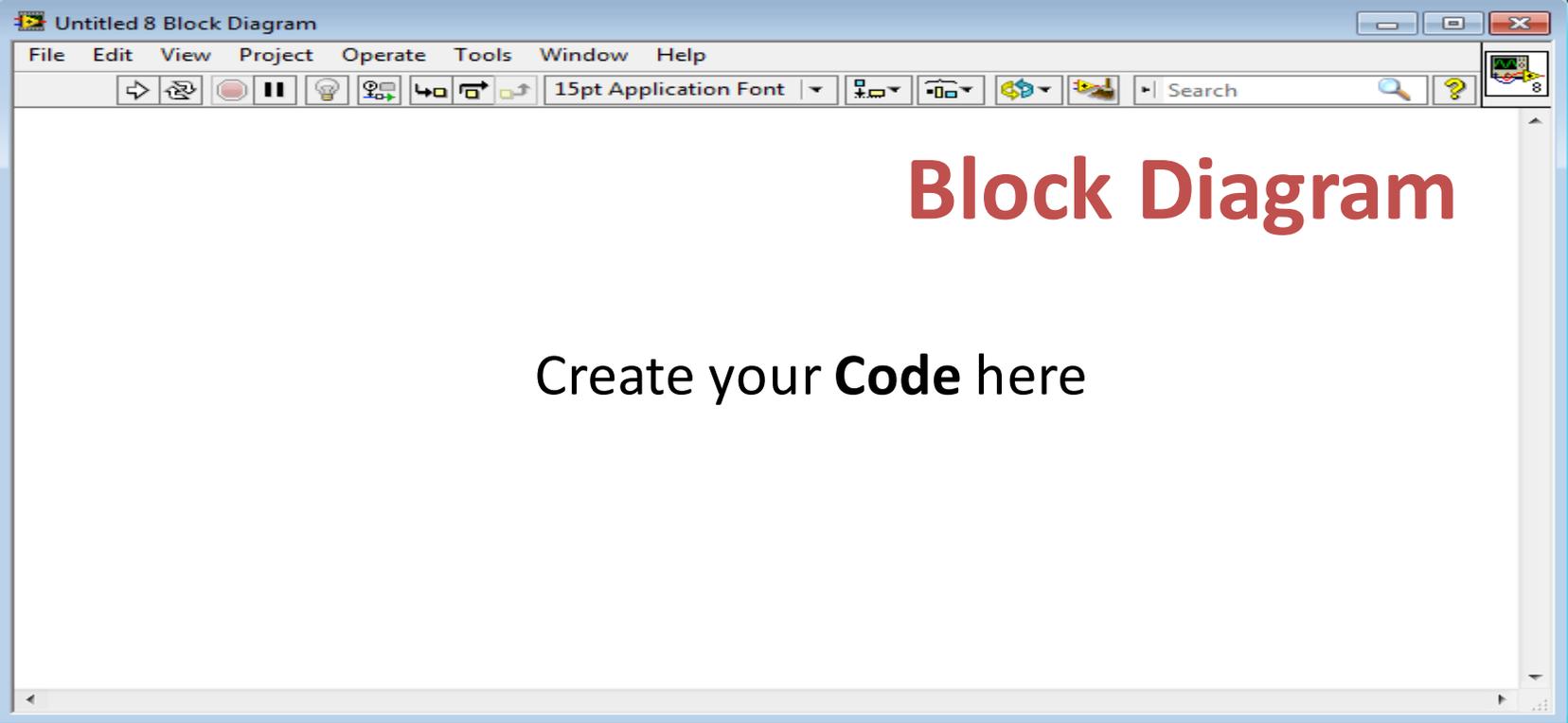
Front Panel

LabVIEW Environment

Note! Both the Front Panel and the Block Diagram are stored in one single file. These files are called **VIs** (because the file extension is “.vi”). VI = Virtual Instruments



Create your **User Interface/HMI** here



Block Diagram

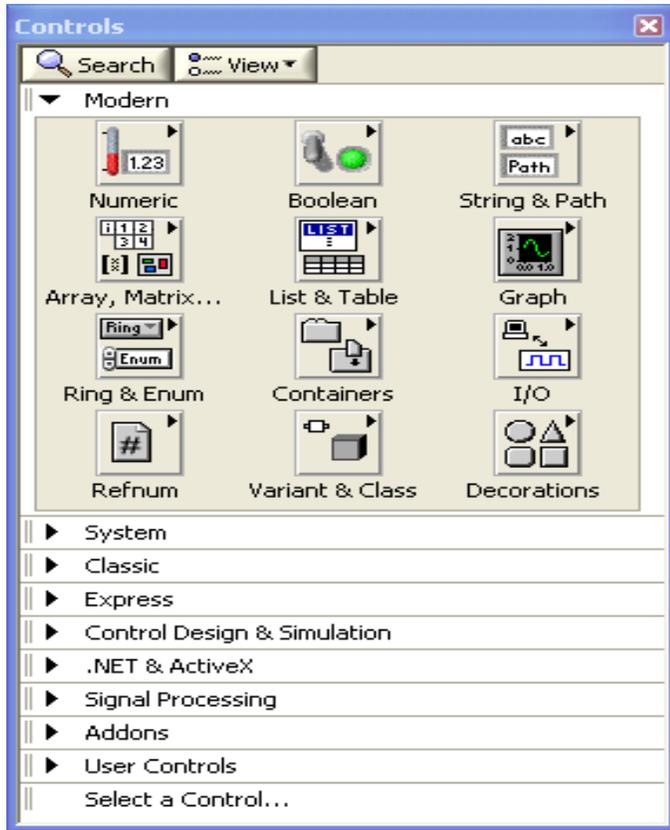
Create your **Code** here

Switch between them: **Ctrl + E**

Controls and Functions Palette



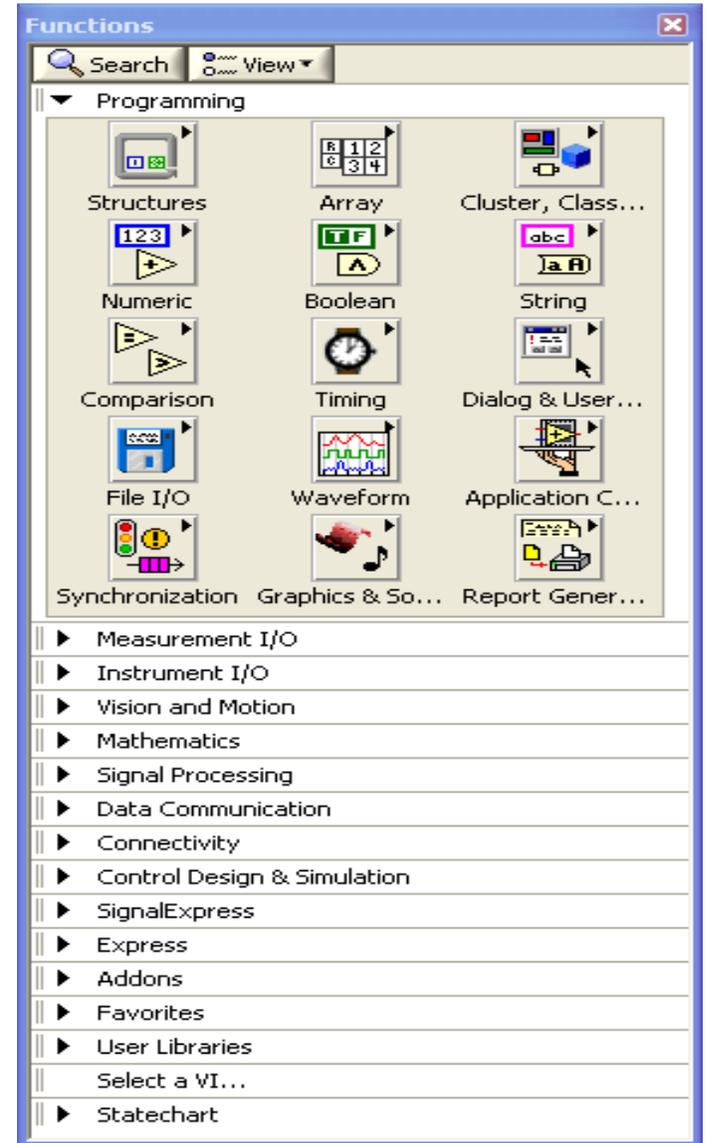
You can "pin" them!



Available only from the **Front Panel**

You create your User Interface with help of these Controls

Right-click on the Front Panel

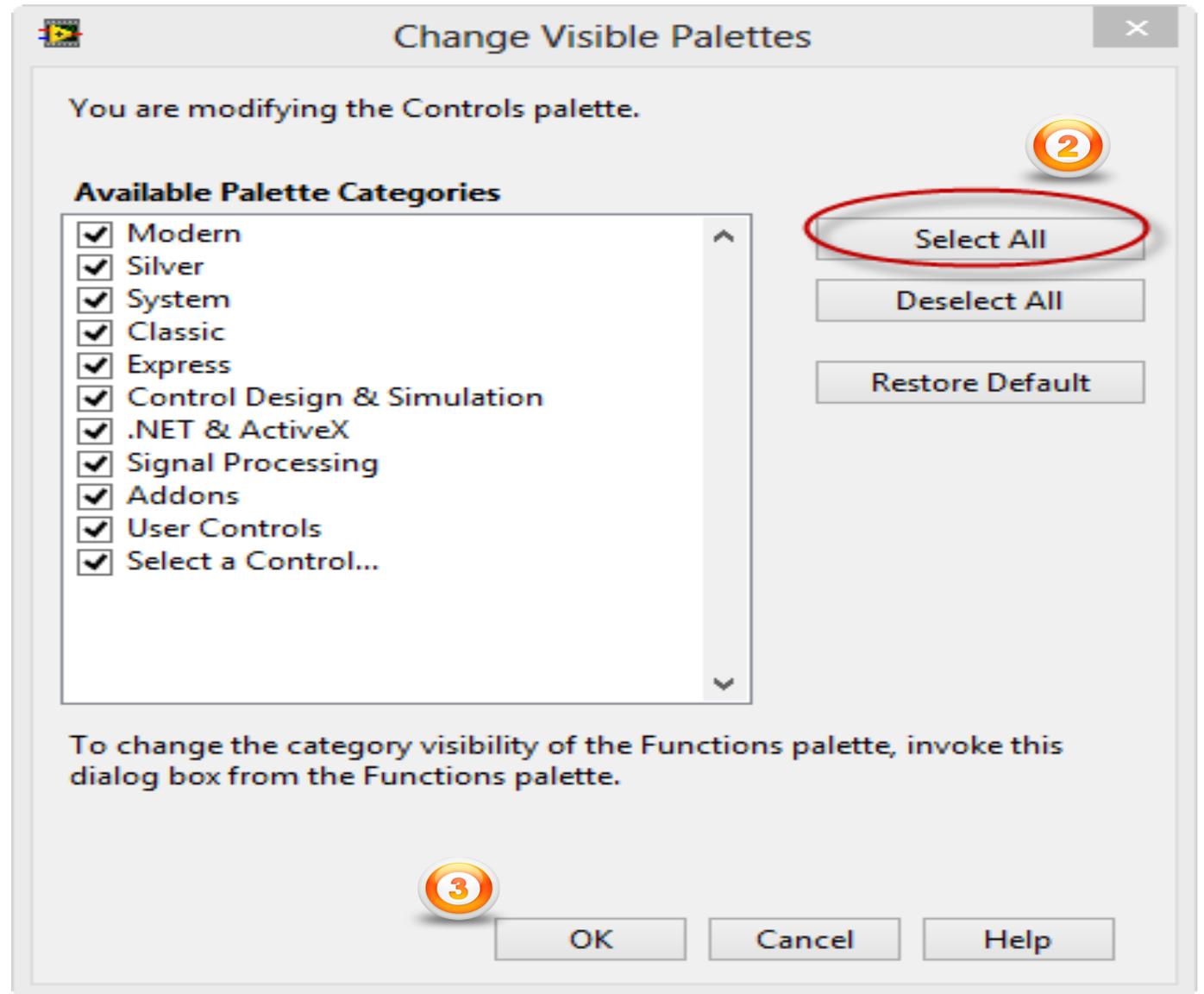
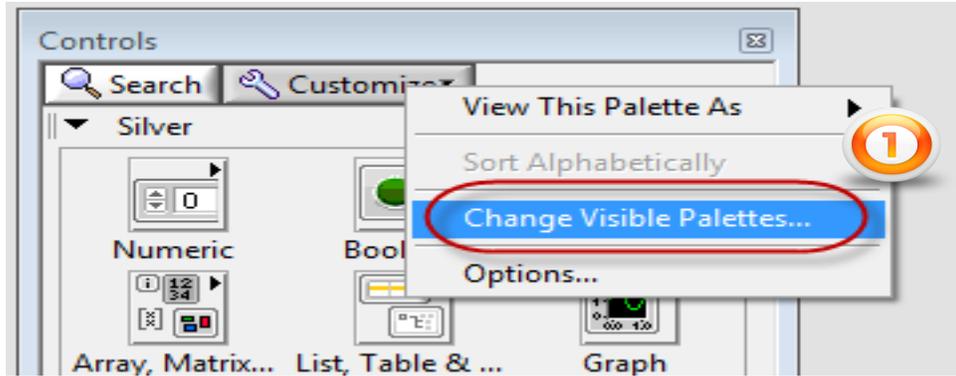


You create your Code with help of these Functions

Available only from the **Block Diagram**

Right-click on the Block Diagram

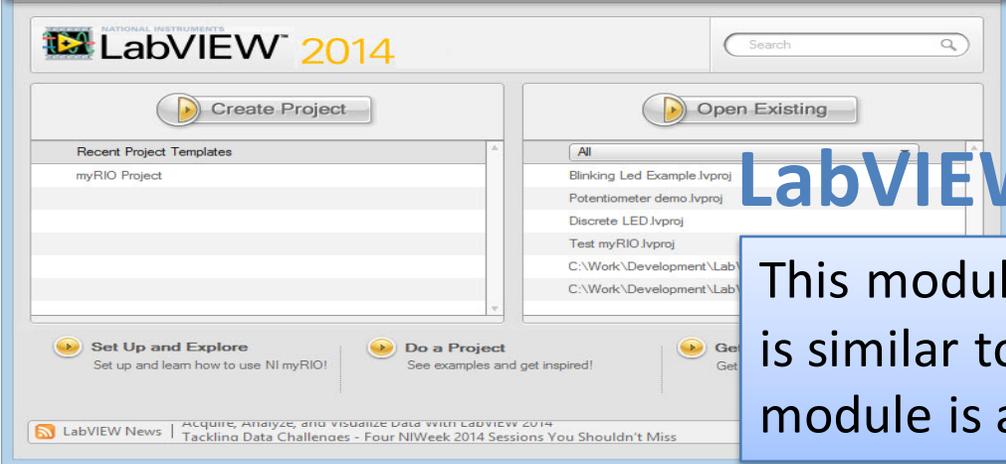
Customizing Controls and Functions Palettes



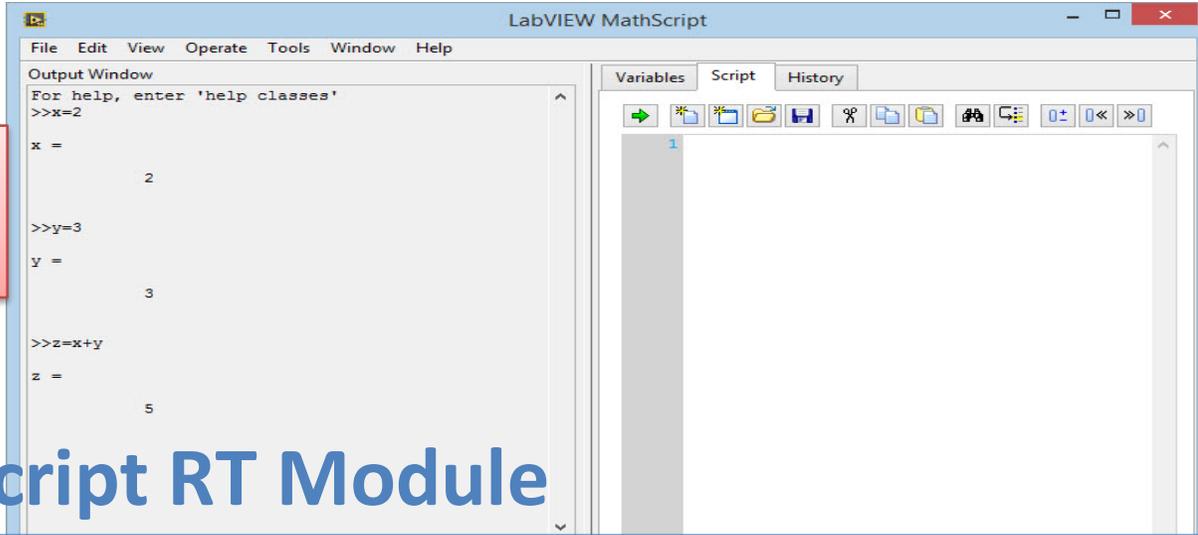
Do this for both the **Controls Palette** and the **Functions Palette**

LabVIEW

This is the core LabVIEW installation that installs the LabVIEW Programming Environment.



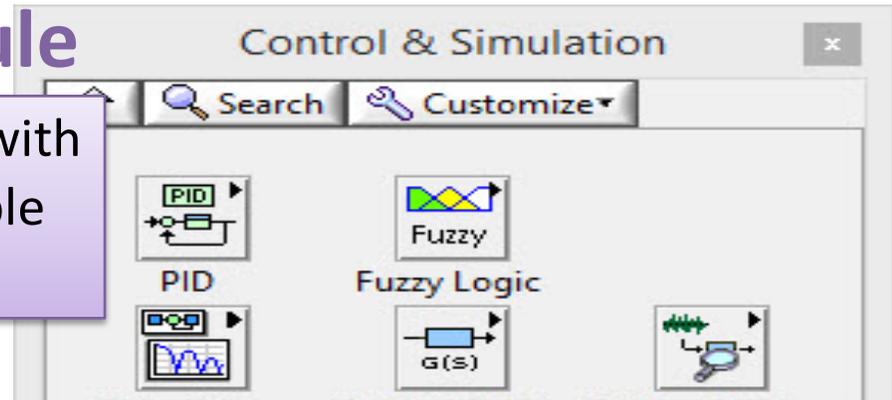
LabVIEW MathScript RT Module



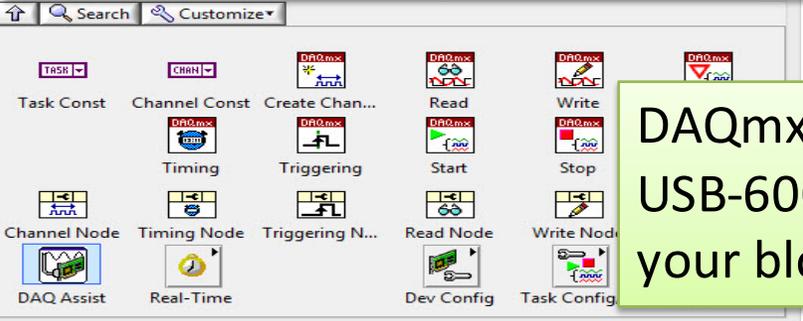
This module is a text-based tool that is very similar to MATLAB. The syntax is similar to MATLAB, you can create and run so-called m files, etc. The module is available from the Tools menu inside LabVIEW.

LabVIEW Control Design and Simulation Module

This module is used for creating Control and Simulation applications with LabVIEW. Here you will find PID controllers, etc. The module is available as a palette on your block diagram.



NI-DAQmx



DAQmx is the Hardware Driver needed in order to use hardware devices like NI USB-6008, NI TC-01, etc. inside LabVIEW. The module is available as a palette on your block diagram.

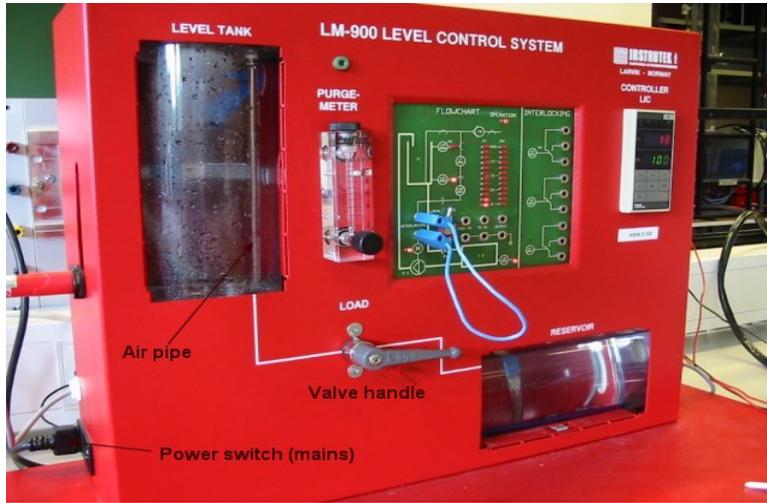


Modelling of Dynamic Systems

Hans-Petter Halvorsen, M.Sc.

Dynamic Systems Examples

Water Tank:



h – Level in the tank

Mathematical Models (differential equations):

Alt 1 (Integrator):
$$\dot{h} = \frac{1}{A} [K_p u - F_{out}]$$

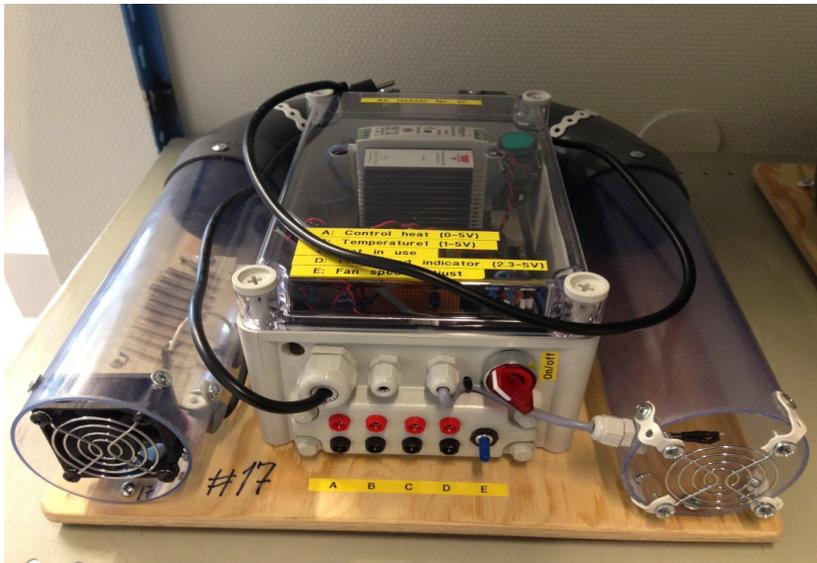
Alt 2 (Time constant/1.order):

$$\dot{h} = \frac{1}{A} [K_p u - K_v h]$$

Alt 3 (Nonlinear):

$$\dot{h} = \frac{1}{A} \left[K_p u - K_v \sqrt{\frac{\rho g h}{G}} \right]$$

Air Heater:



T – Temperature in the tube

$$\dot{T}_{out} = \frac{1}{\theta_t} \{-T_{out} + [K_h u(t - \theta_d) + T_{env}]\}$$

Dynamic Systems

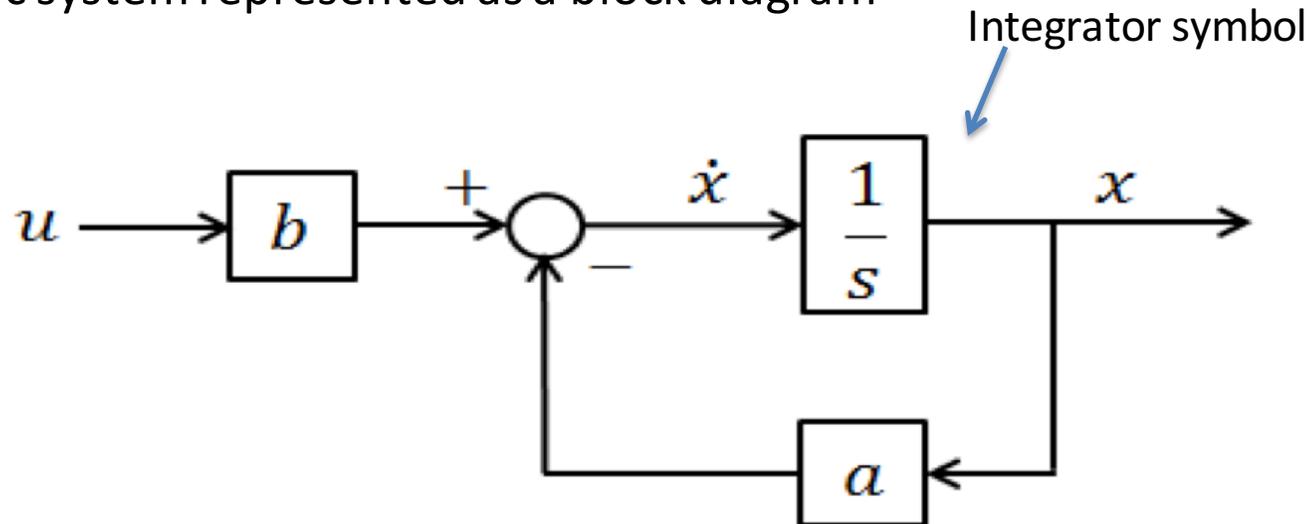
Dynamic system represented as a differential equation (1.order system):

$$\frac{dx}{dt} = -ax + bu$$

Note

We can "easily" create a block diagram from the differential equation(s)

Dynamic system represented as a block diagram



When we have the block diagram for the system, we can easily implement it in LabVIEW

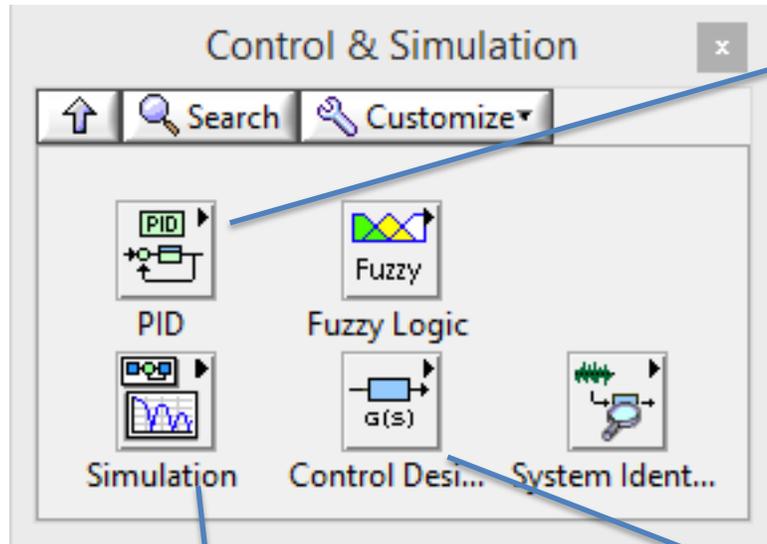


Simulation in LabVIEW

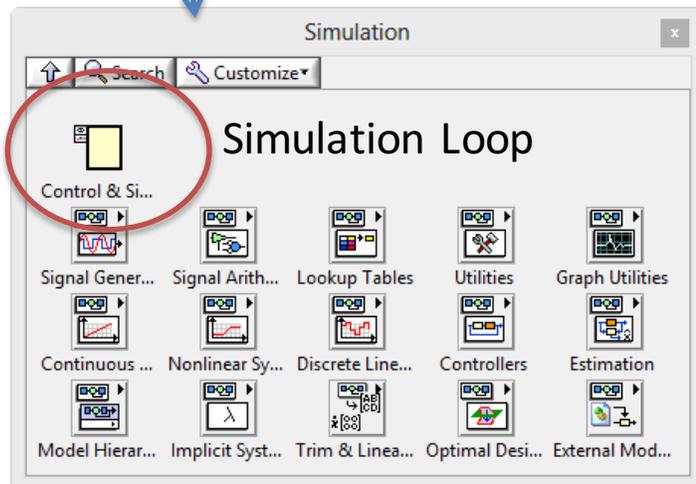
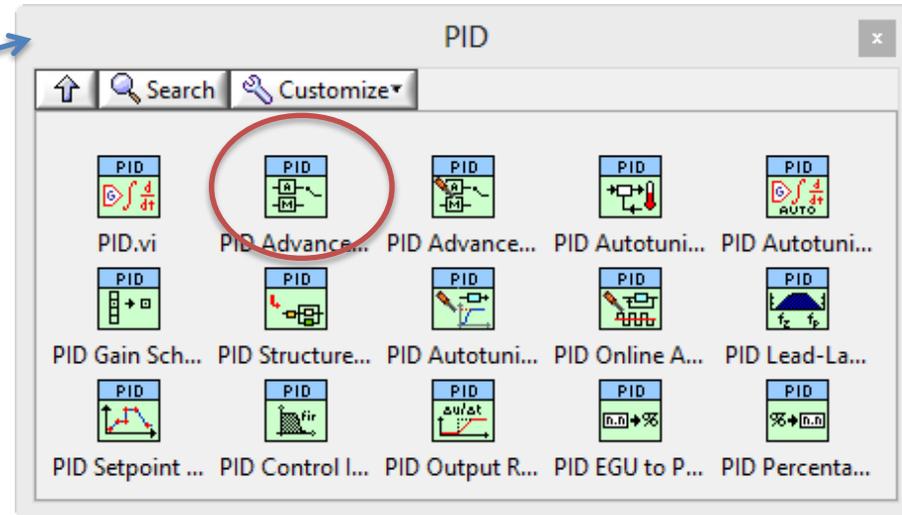
Hans-Petter Halvorsen, M.Sc.

Control and Simulation in LabVIEW

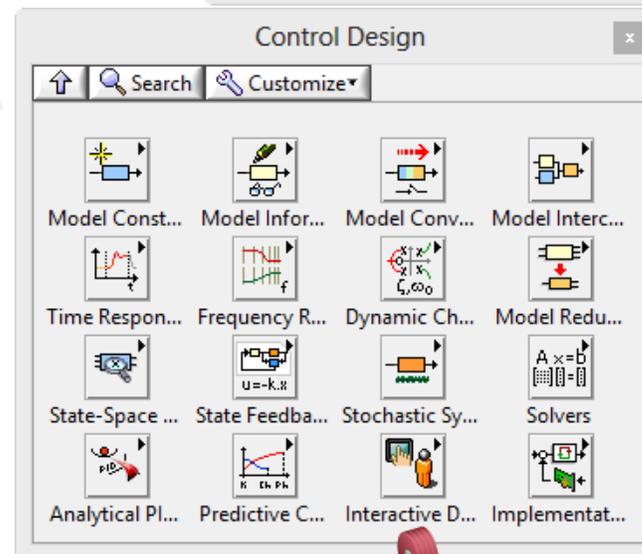
Control Design & Simulation Palette in LabVIEW



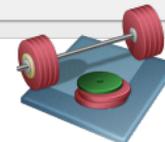
PID Palette in LabVIEW



Simulation Palette in LabVIEW

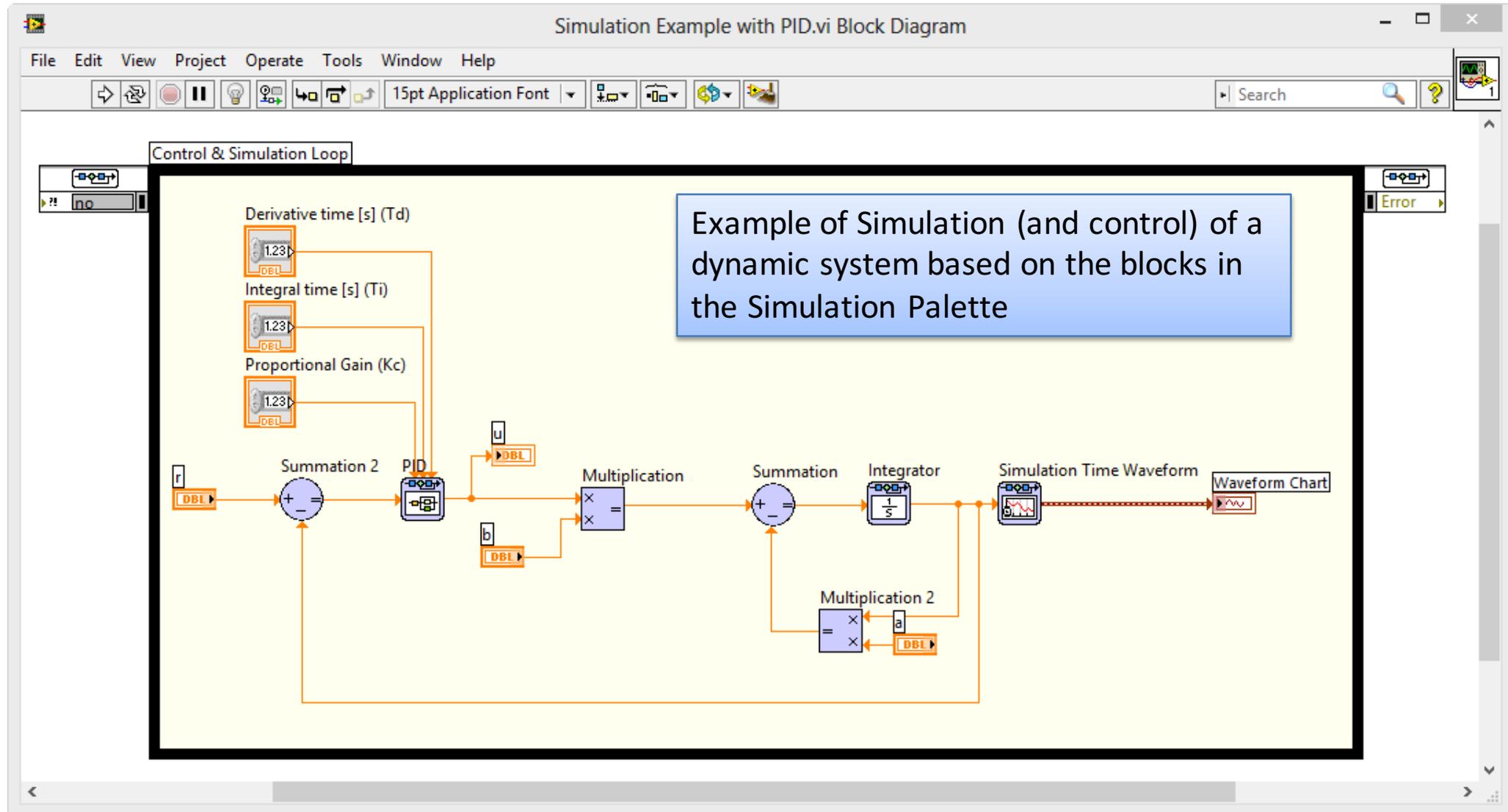


Control Design Palette in LabVIEW



Check that you have all these palettes. Open the different subpalettes, etc.

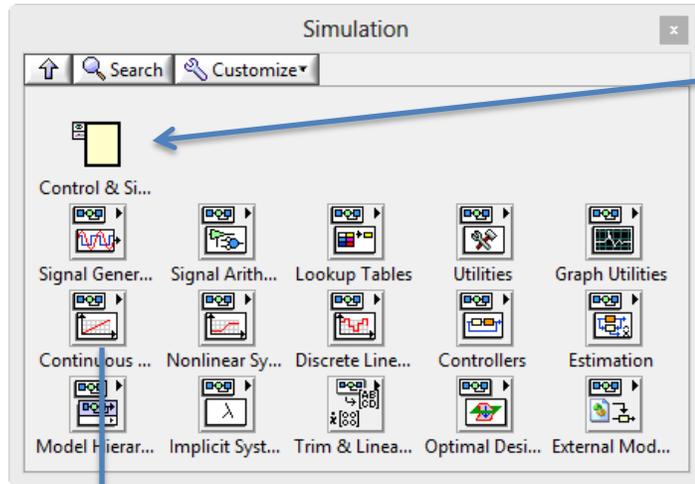
LabVIEW Control and Simulation Example



We are going to learn to create such a system (and much more)!

The Simulation palette in LabVIEW

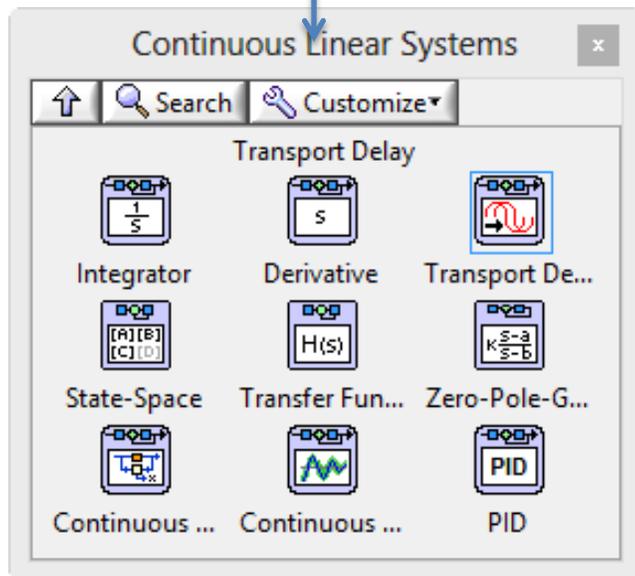
Simulation Palette in LabVIEW



Simulation Loop: Similar to a While Loop, but customized for used together with the Simulation Blocks available in LabVIEW

Different Simulation Blocks by Category

- Continuous Systems
- Discrete Systems
- Nonlinear Systems
- etc.





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LabVIEW Example

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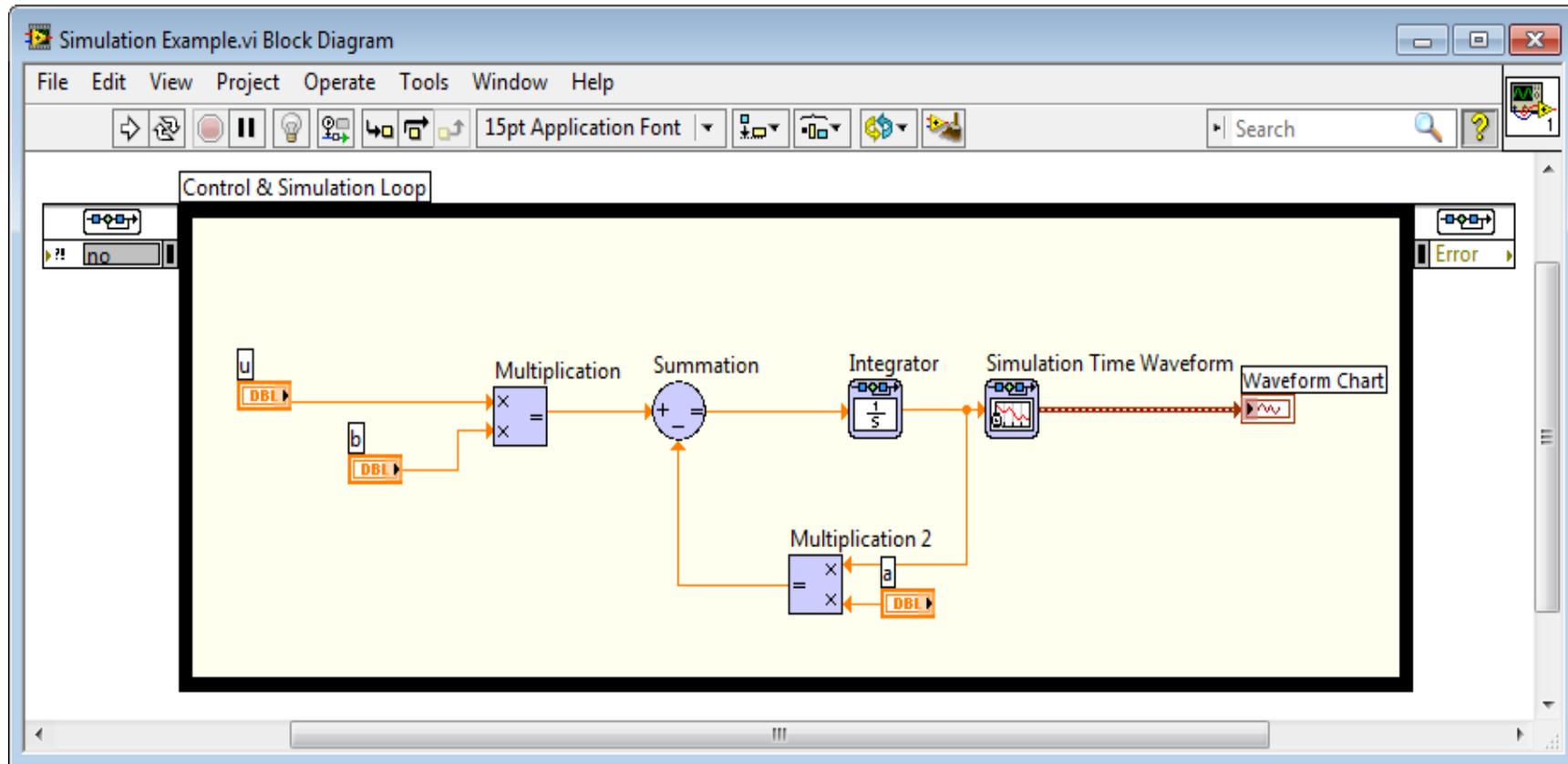
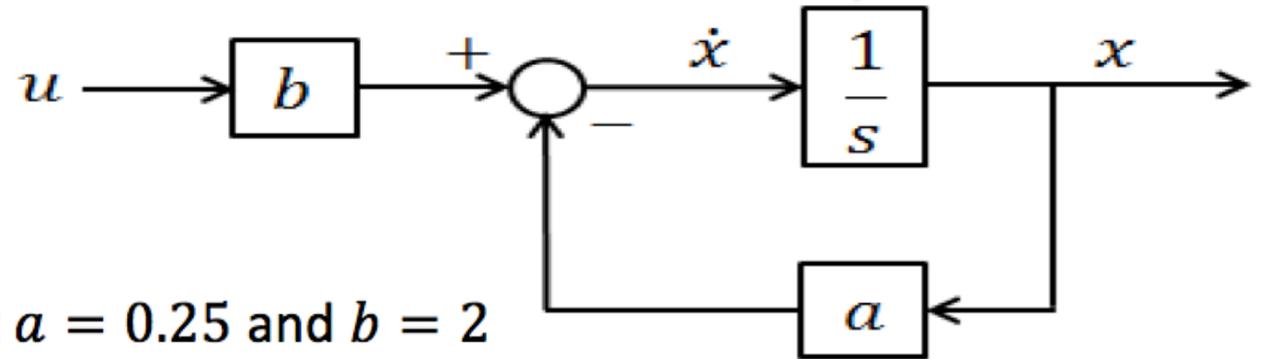
Simulation Example

Dynamic system represented as a differential equation

$$\dot{x} = -ax + bu$$



set $a = 0.25$ and $b = 2$



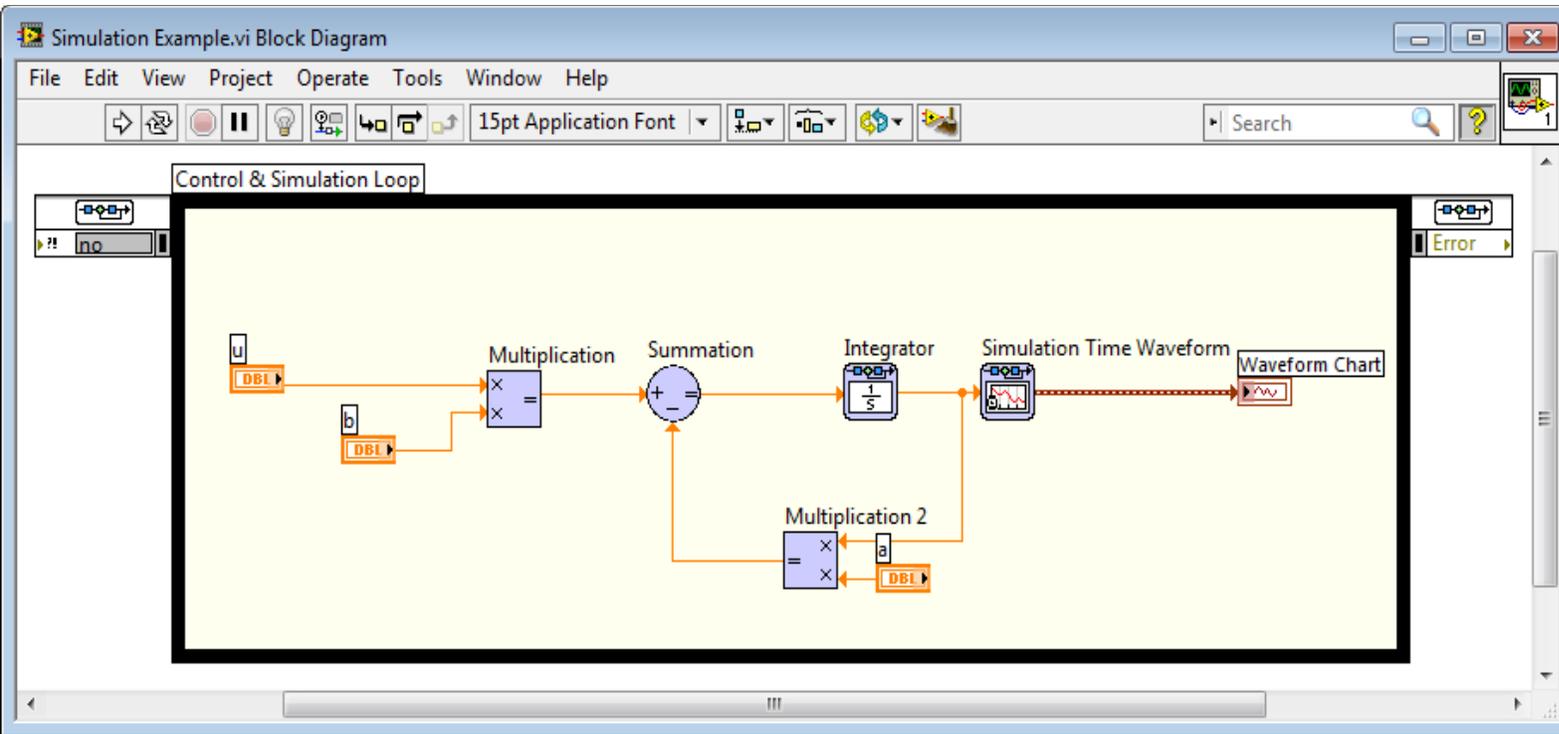
Simulation Example - Configuration

In the example the following simulation parameters could be used (right-click on the Simulation Loop border and select “Configure Simulation parameters...”):

The 'Configure Simulation Parameters' dialog box is shown with the 'Simulation Parameters' tab selected. The 'Timing Parameters' tab is also visible. The 'Simulation Time' section has 'Initial Time (s)' set to 0 and 'Final Time' set to 20. The 'Solver Method' is 'ODE Solver' with 'Runge-Kutta 23 (variable)' selected and 'Nan/Inf Check' unchecked. The 'Continuous Time Step and Tolerance' section has 'Initial Step Size (s)' at 0,01, 'Minimum Step Size (s)' at 1E-10, 'Maximum Step Size (s)' at 1, 'Relative Tolerance' at 0,001, and 'Absolute Tolerance' at 1E-7. The 'Discrete Time Step' section has 'Discrete Step Size (s)' at 0,1 and 'Auto Discrete Time' checked. The 'Signal Collection' section has 'Decimation' set to 0. Buttons for 'OK', 'Cancel', and 'Help' are at the bottom.

The 'Configure Simulation Parameters' dialog box is shown with the 'Timing Parameters' tab selected. The 'Enable Synchronized Timing' section has 'Synchronize Loop to Timing Source' unchecked. The 'Timing Source' section has 'Source type' set to '1 kHz Clock' in a list box, and 'Source' set to '1 kHz' in a text field. The 'Loop Timing Attributes' section has 'Period' at 1000, 'Offset / Phase' at 0, 'Deadline' at -1, 'Auto Period' unchecked, 'Priority' at 100, and 'Timeout (ms)' at -1. The 'Processor Assignment' section has 'Mode' set to 'Automatic' and 'Processor' at -2. Buttons for 'OK', 'Cancel', and 'Help' are at the bottom.

Simulation Example - Solutions



Try with different values for u

$$\dot{x} = -ax + bu$$

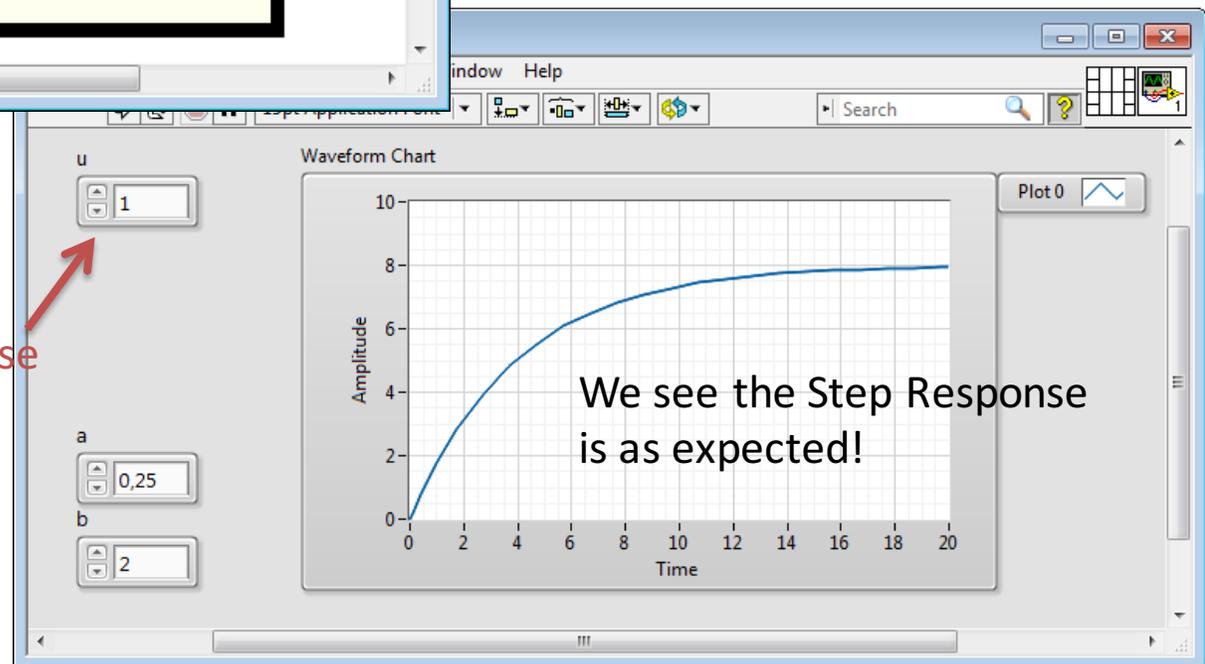
set $a = 0.25$ and $b = 2$

Step Response

Correct results? – Check static response:

$$0 = -ax_s + bu_s$$

$$x_s = \frac{b}{a}u_s = \frac{2}{0.25}1 = 8$$



We see the Step Response is as expected!

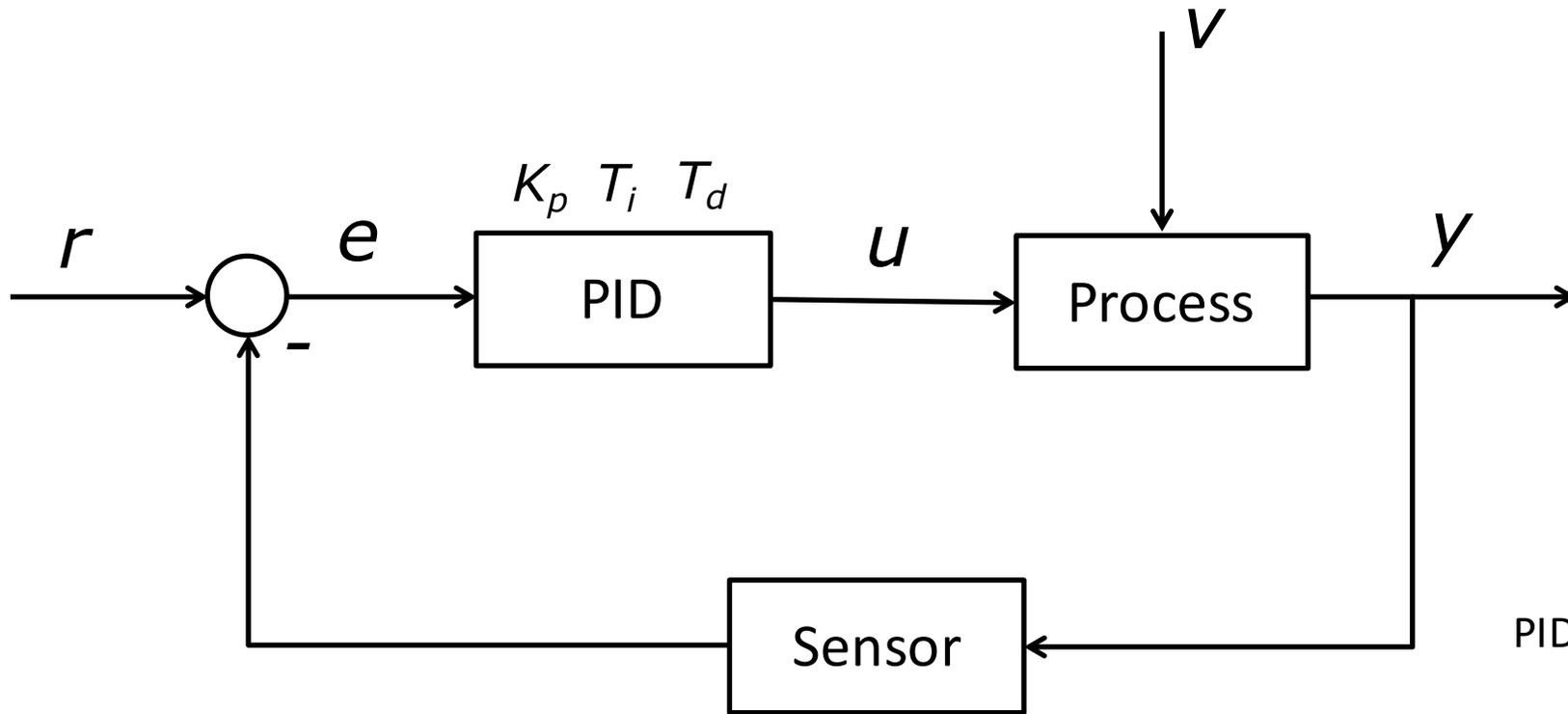
DEMO



PID Control in LabVIEW

Hans-Petter Halvorsen, M.Sc.

Control System



PID Algorithm:

$$u(t) = K_p e + \frac{K_p}{T_i} \int_0^t e d\tau + K_p T_d \dot{e}$$

r – Reference Value, SP (Setpoint), SV (Set Value)

y – Measurement Value (MV), Process Value (PV)

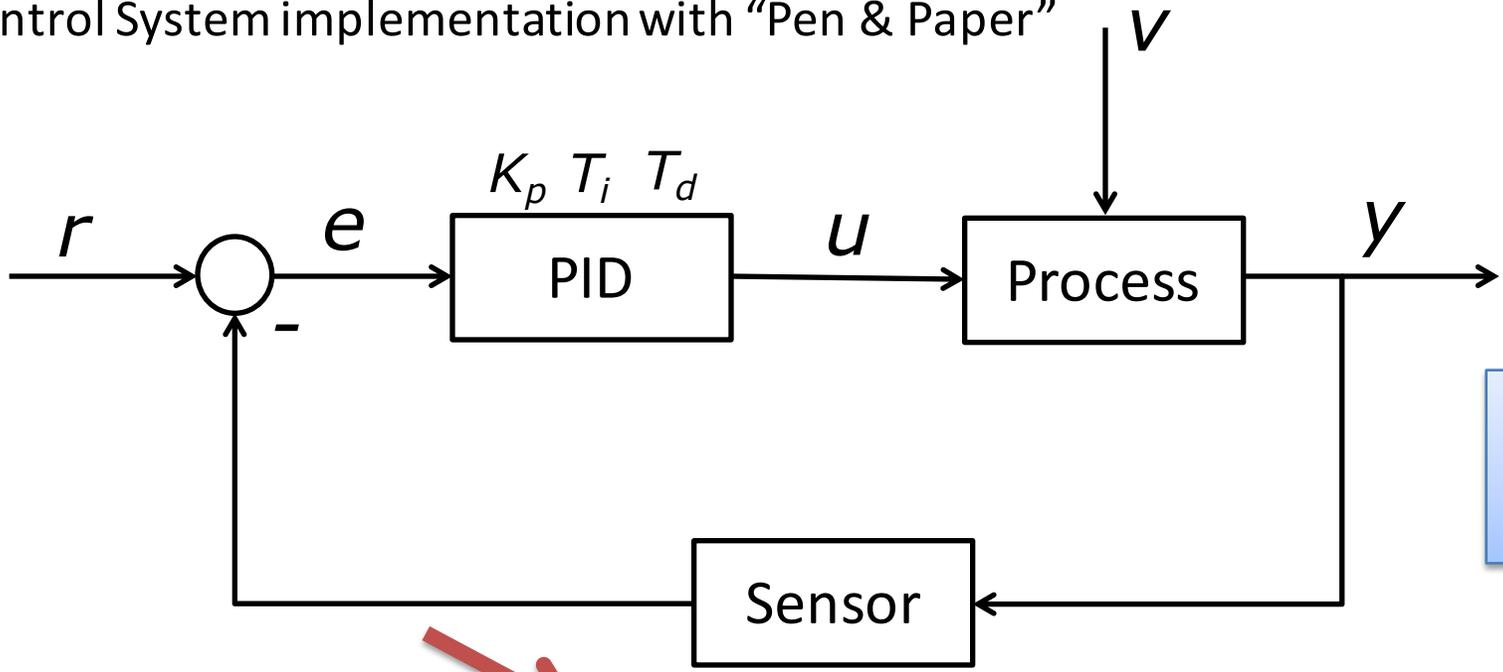
e – Error between the reference value and the measurement value ($e = r - y$)

v – Disturbance, makes it more complicated to control the process

K_p , T_i , T_d – PID parameters



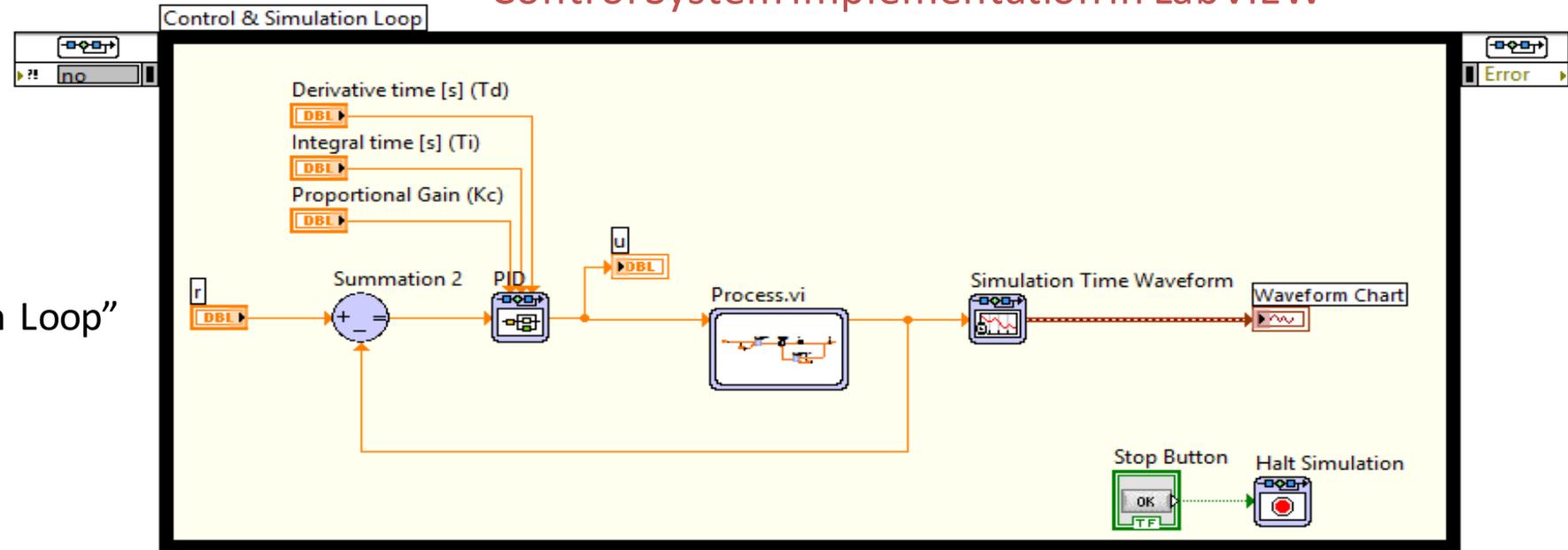
Control System implementation with "Pen & Paper"



The transition from "paper" to LabVIEW is easy, because the implementation is very similar to the "paper" version

Control System implementation in LabVIEW

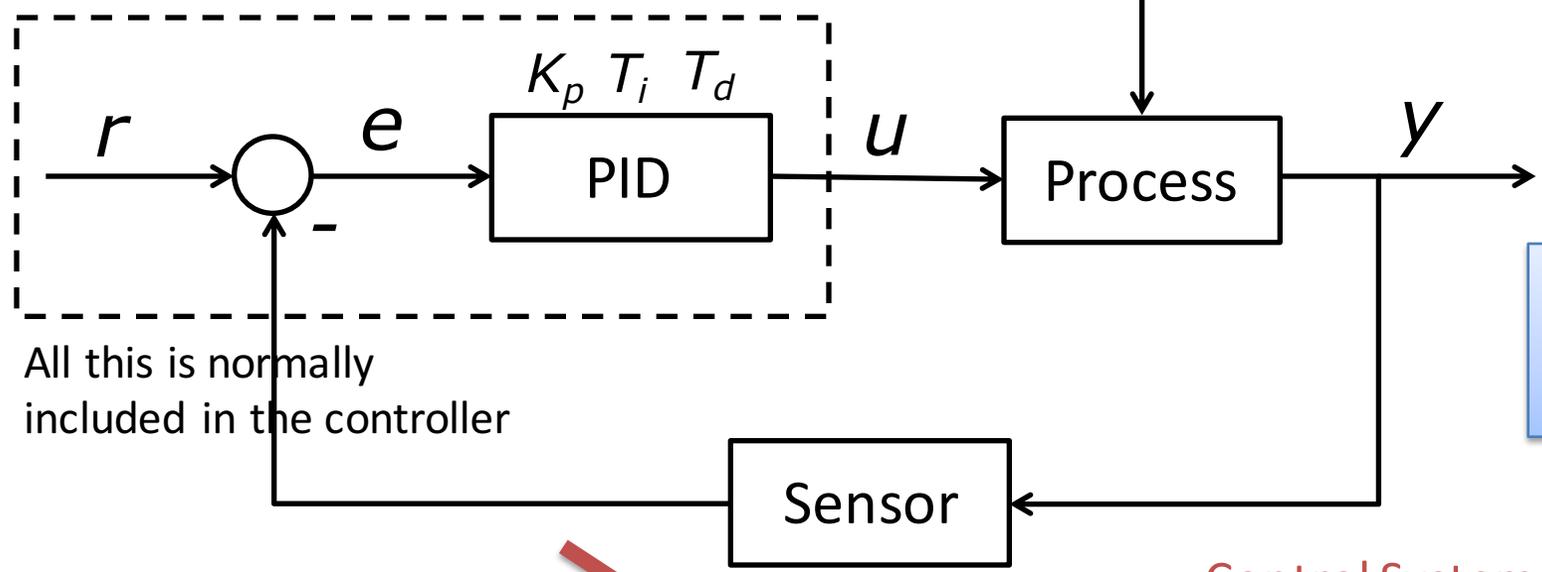
Here we have used the "Simulation Loop"





Control System implementation with "Pen & Paper"

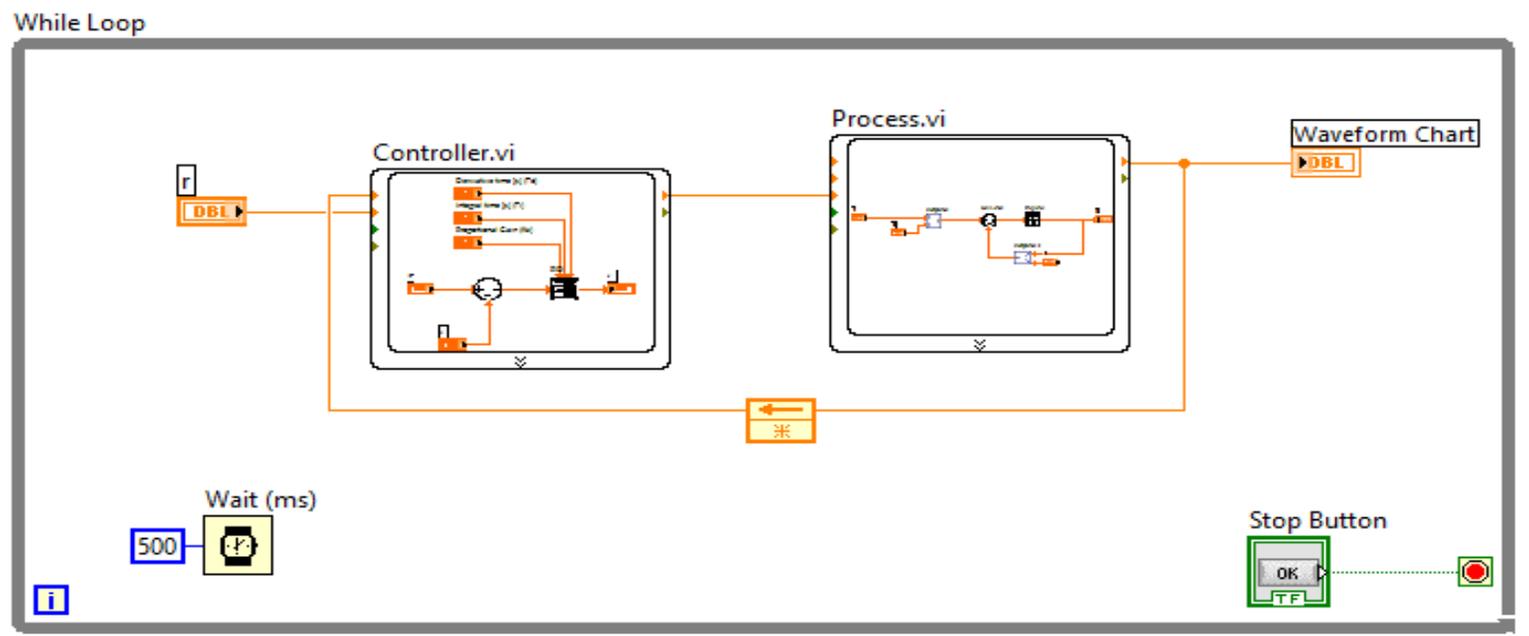
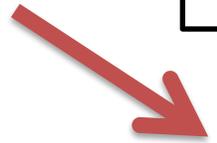
Controller



All this is normally included in the controller

The transition from "paper" to LabVIEW is easy, because the implementation is very similar to the "paper" version

Control System implementation in LabVIEW

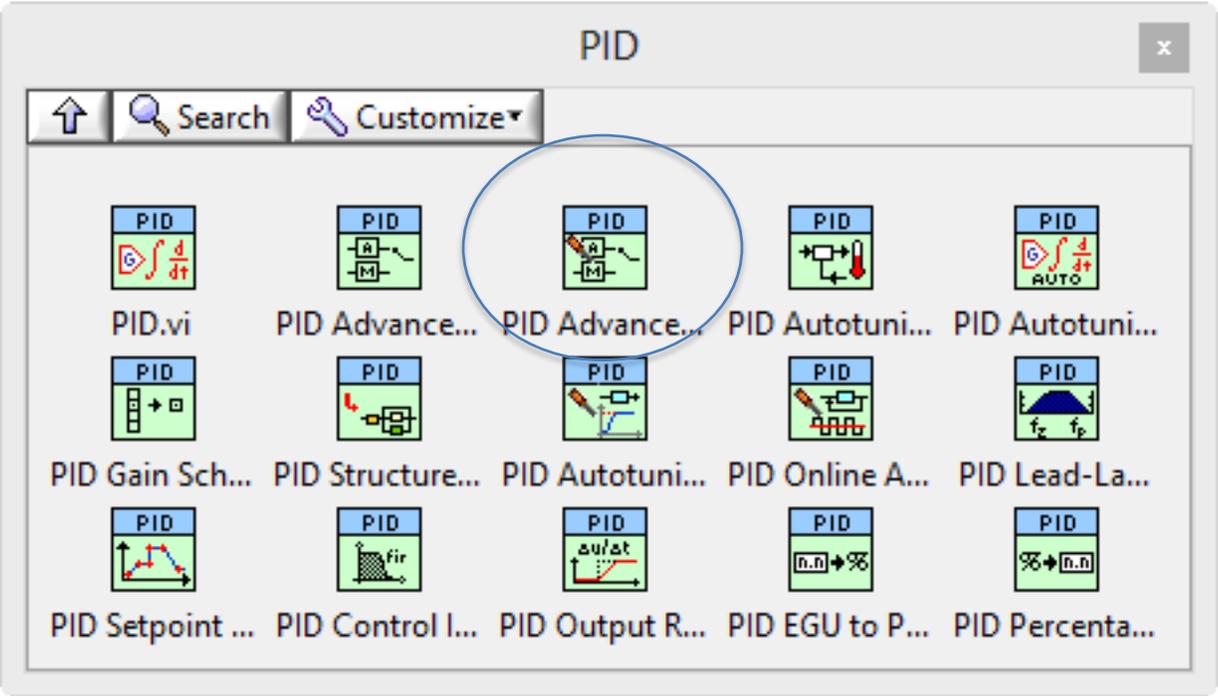


Here we have used an ordinary While Loop (which is recommended!)

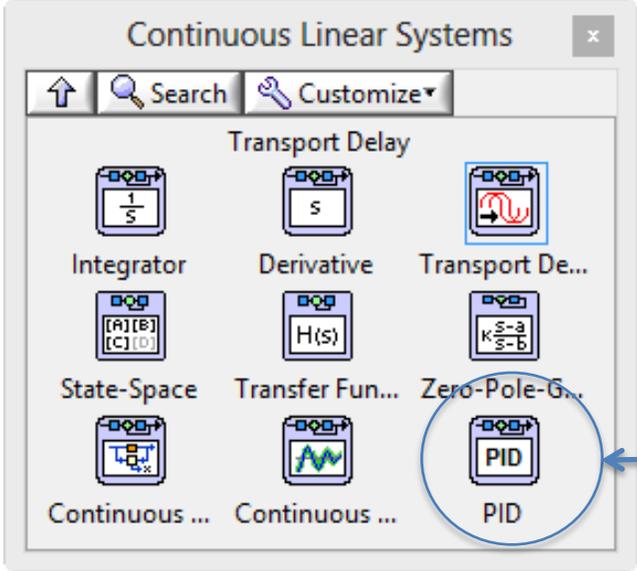
PID Control in LabVIEW

Alternative 1:

PID Palette in LabVIEW (PID Toolkit)

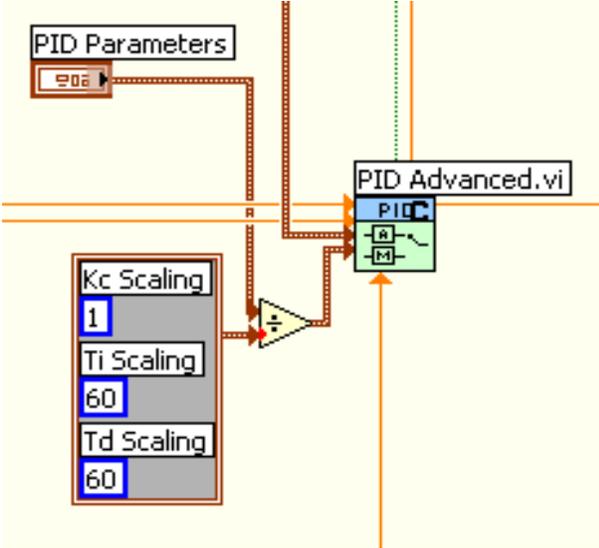


Alternative 2:



This alternative uses seconds!

Note! The functions “PID.vi” and “PID Advanced.vi” requires that T_i and T_d are in minutes, while it’s normal to use seconds as the unit for these parameters. You can use the following piece of code in order to transform them:
This means we enter values for T_i and T_d in secons on the Front Panel and the values are converted to minutes in the code.





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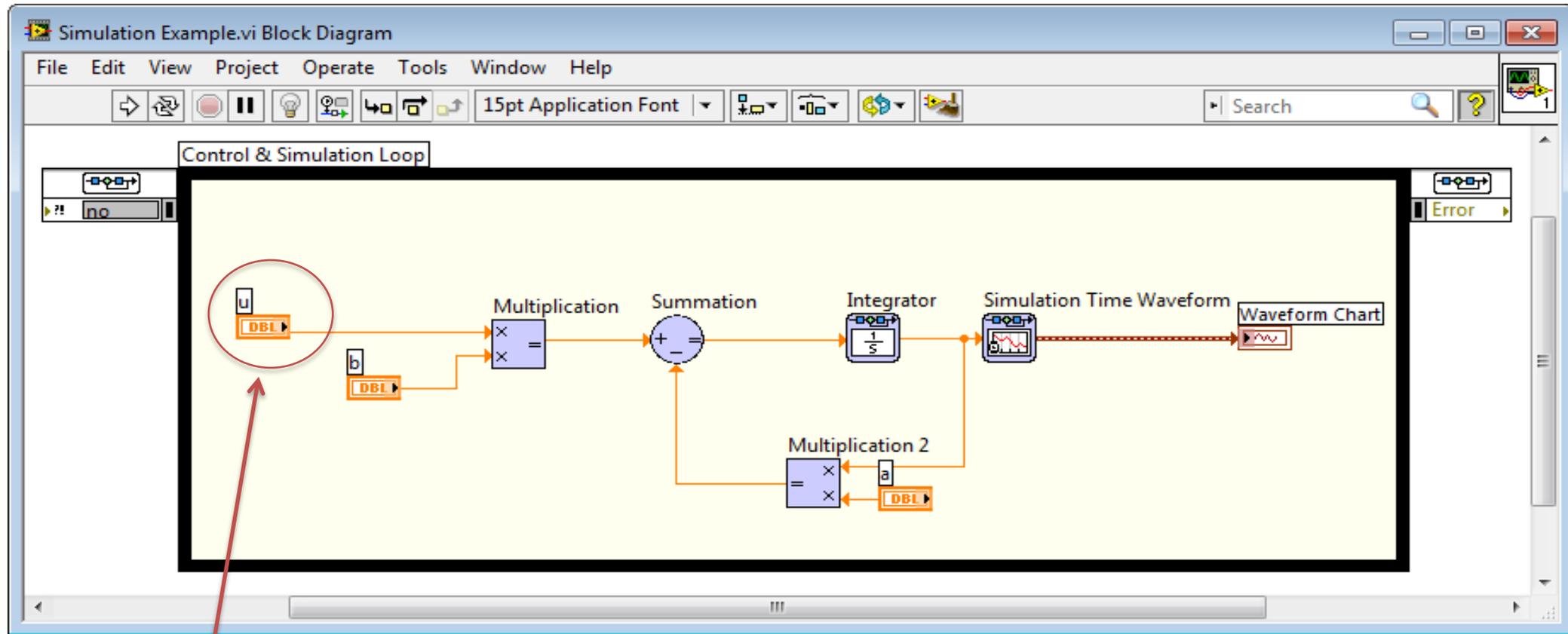


LabVIEW Example

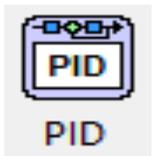
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LabVIEW PID Example

$$\dot{x} = -ax + bu \quad \text{set } a = 0.25 \text{ and } b = 2$$



We will replace u in the previous example with the built-in PID Controller (use [Alternative 2](#))

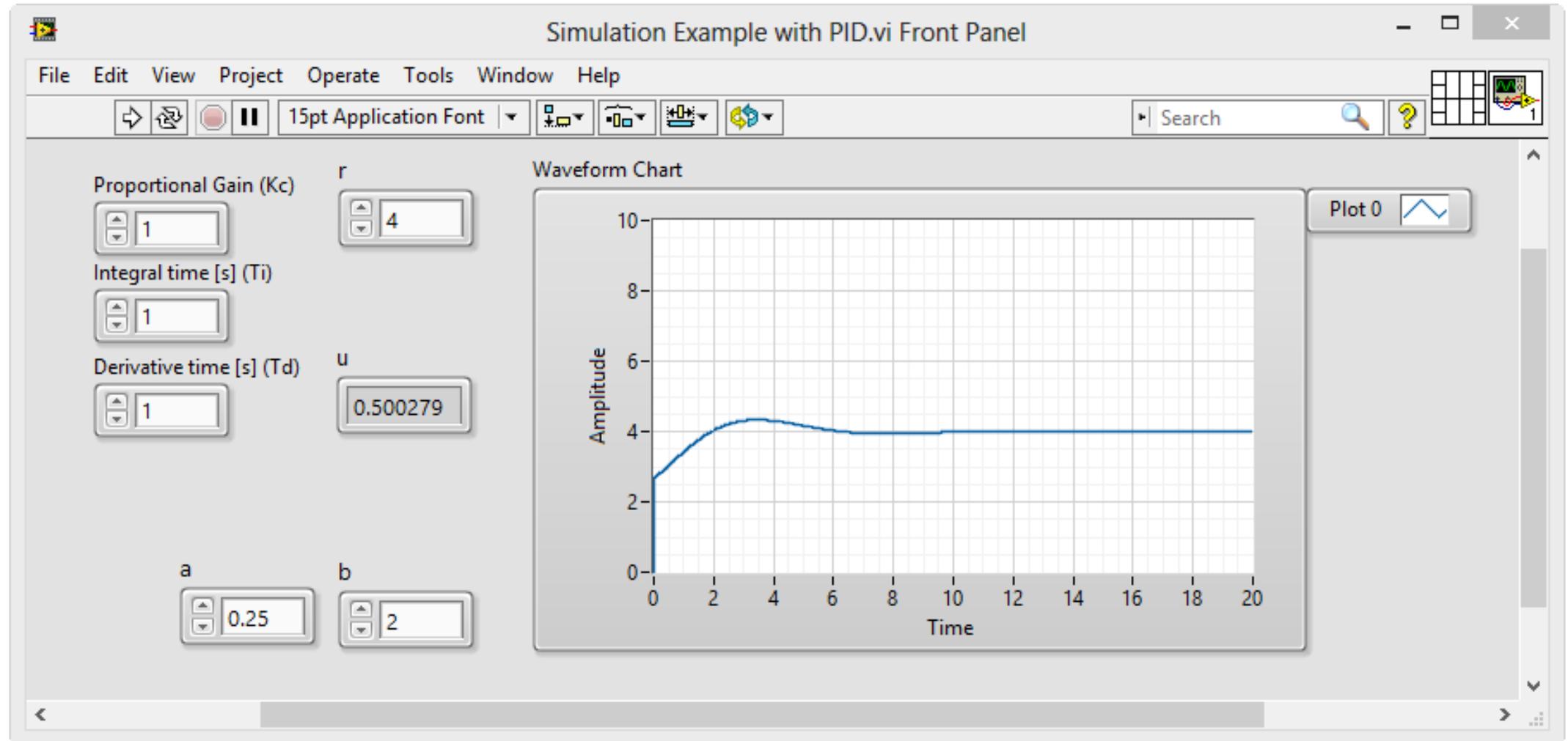


PID Example - Solutions

$$\dot{x} = -ax + bu$$

set $a = 0.25$ and $b = 2$

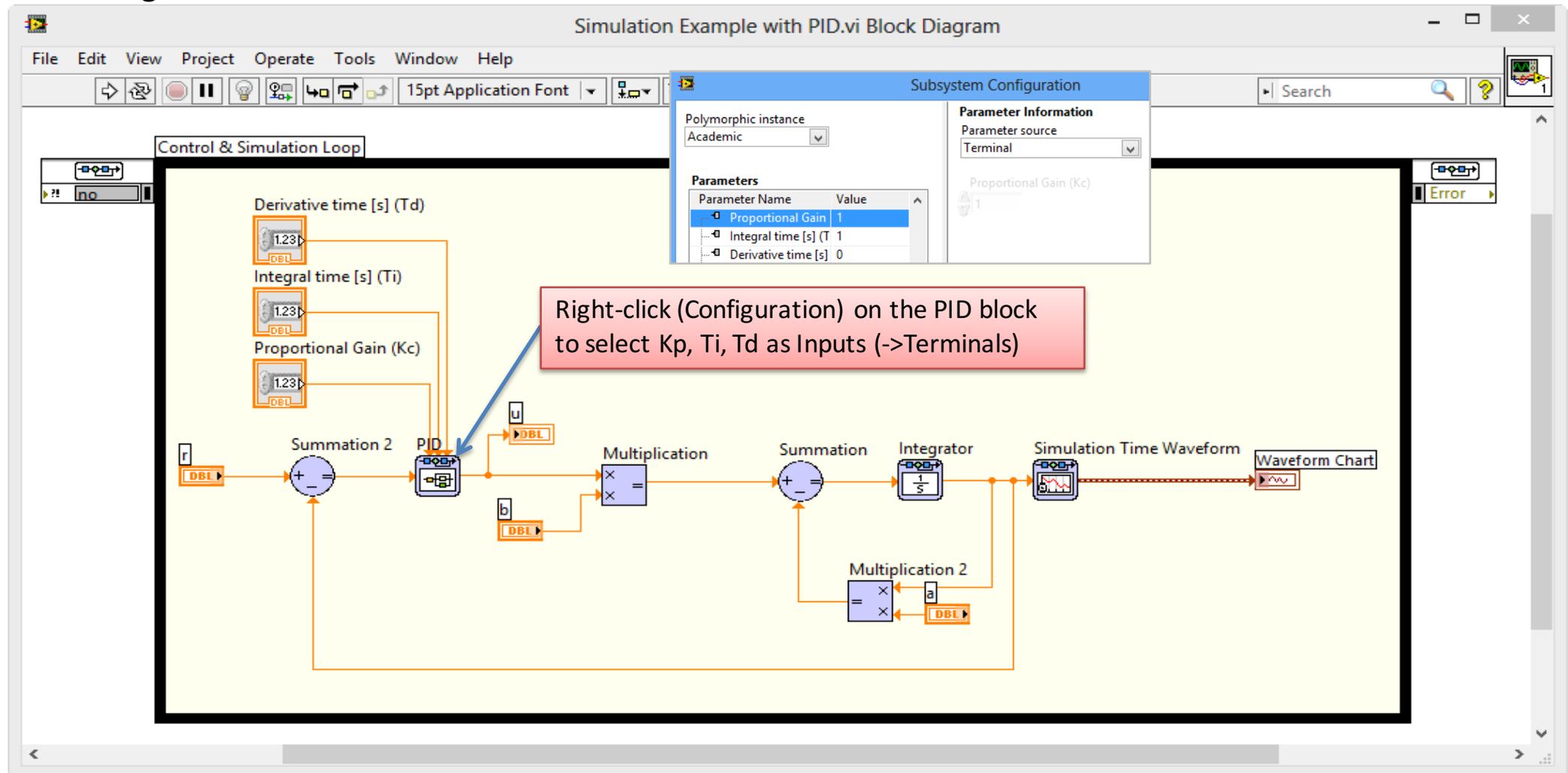
Front Panel:



PID Example - Solutions

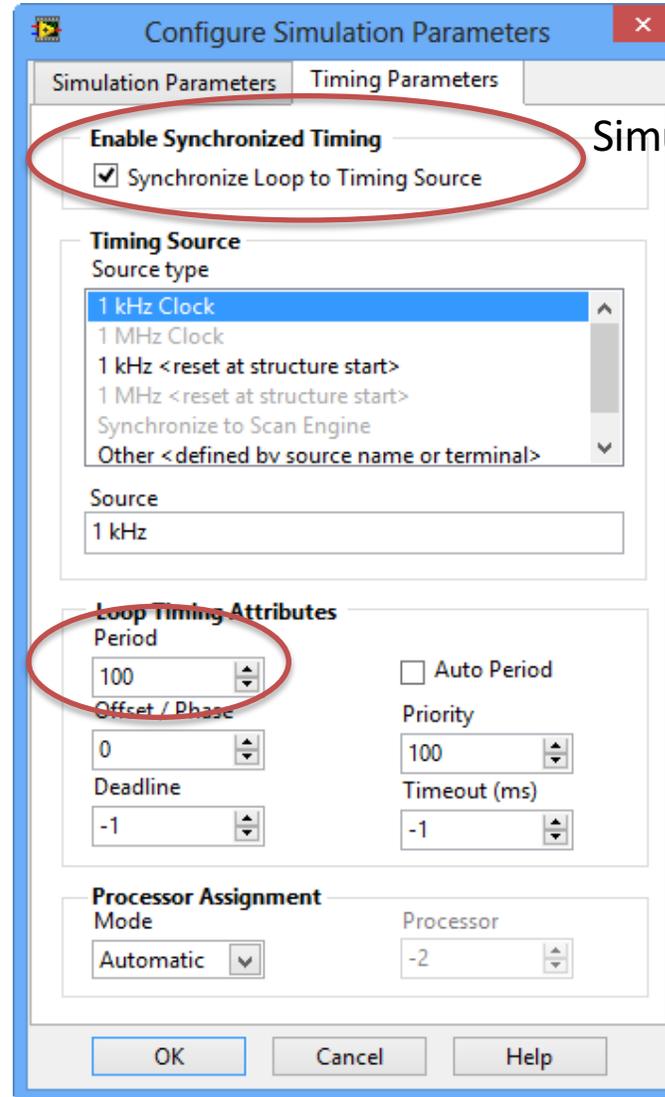
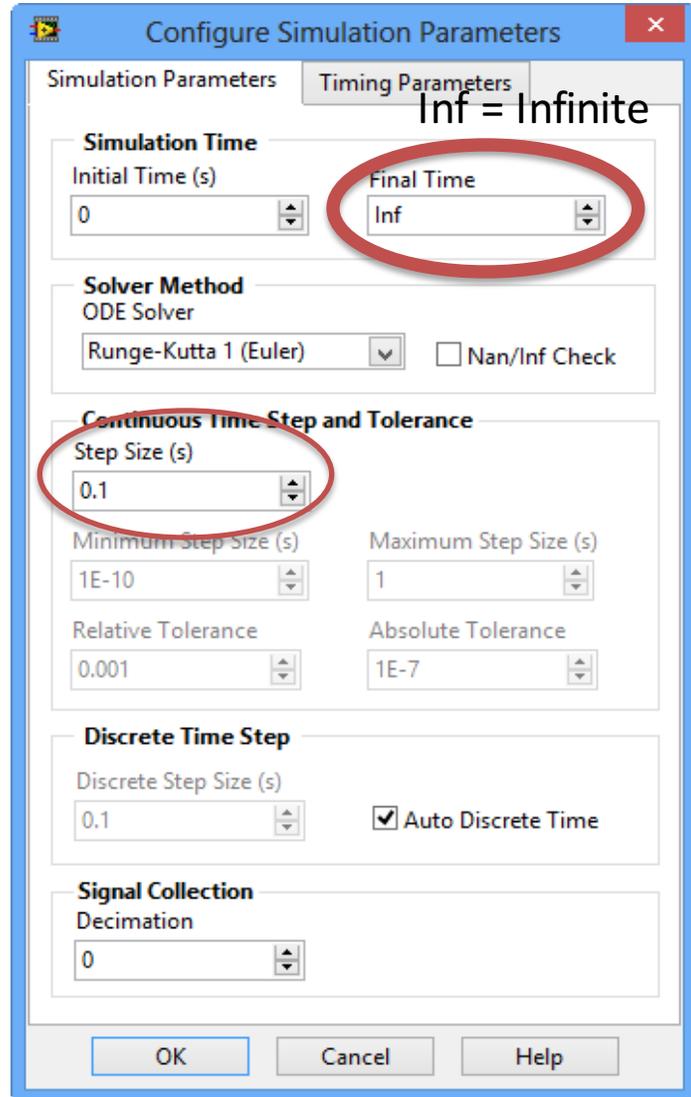
$$\dot{x} = -ax + bu \quad \text{set } a = 0.25 \text{ and } b = 2$$

Block Diagram:



DEMO

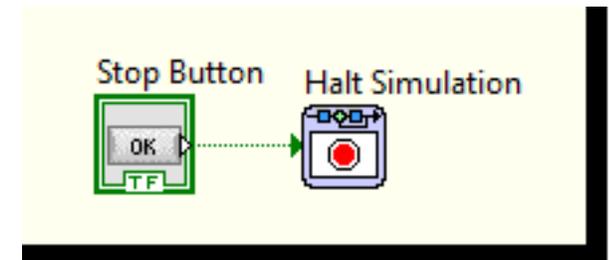
Next Step: Continuous Simulation



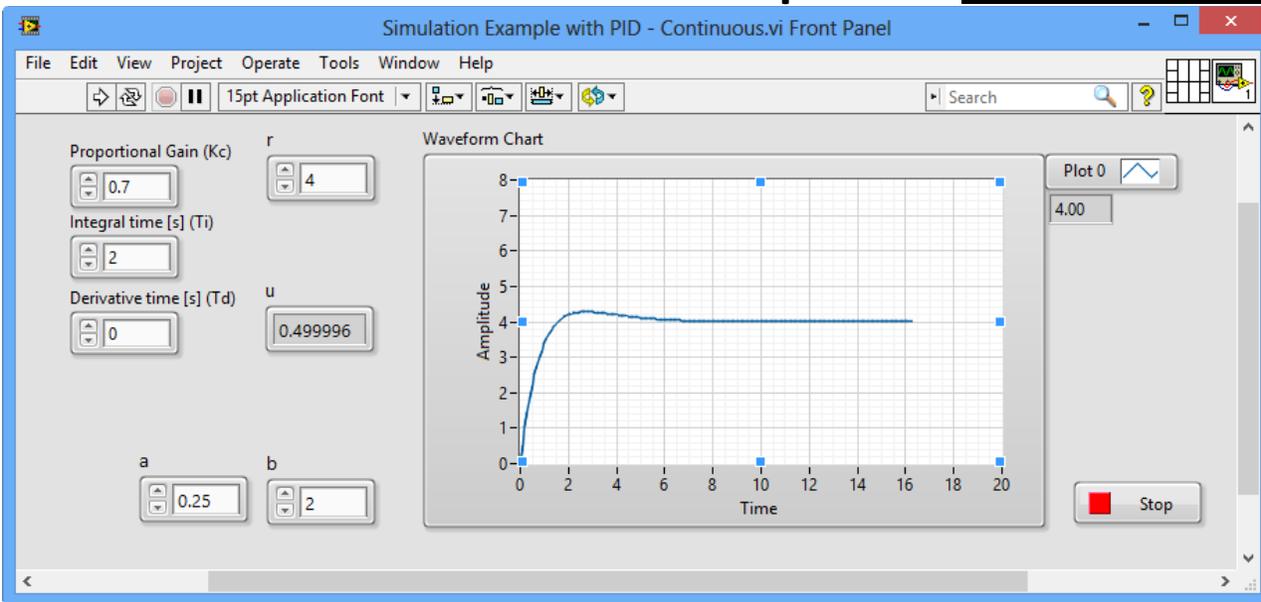
Simulation in "Real Time"

Right-click on the Simulation Loop border and select "Configure Simulation Parameters..."

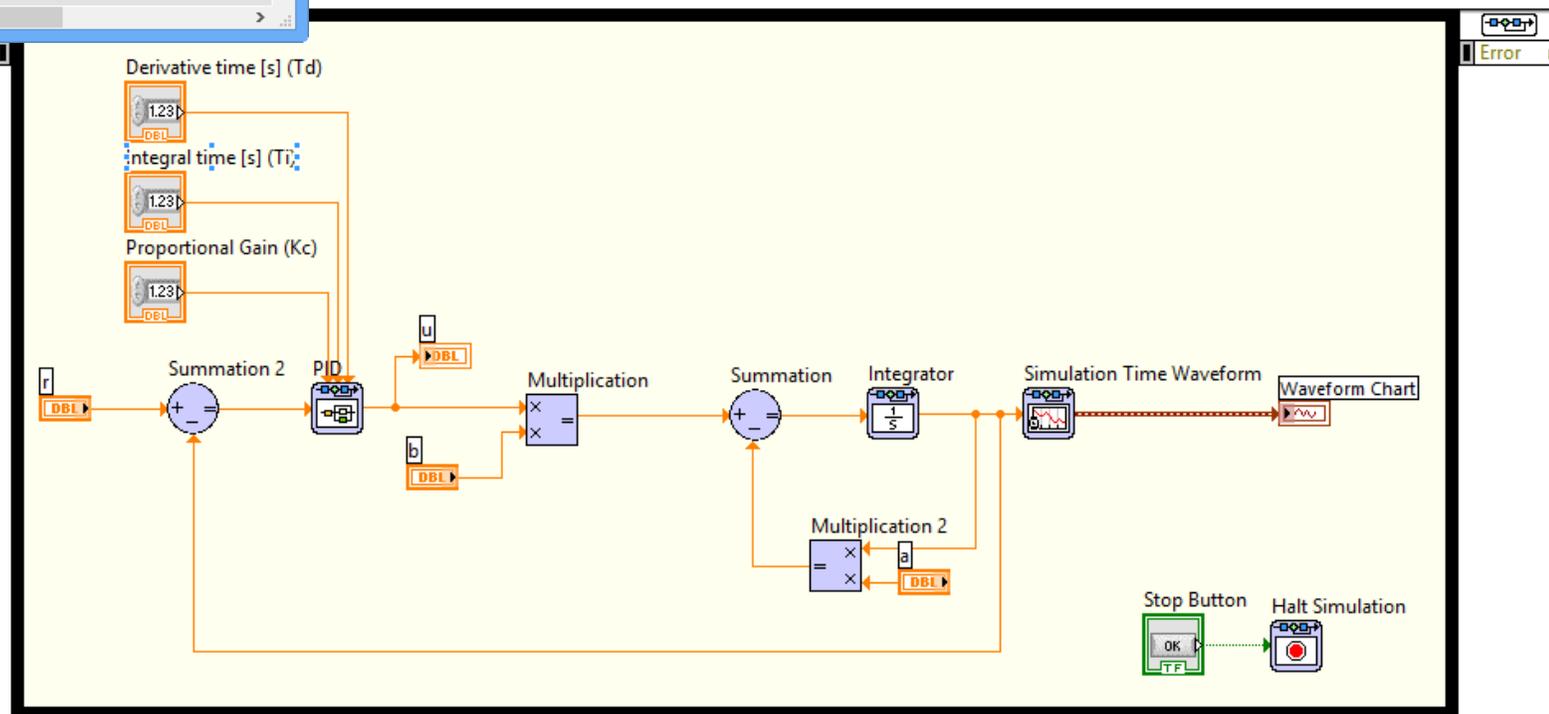
Add a Stop Button and a "Halt Simulation" block



PID Example – Continuous Simulation - Solution



The Simulation now runs until you press the Stop button



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Simulation Subsystems

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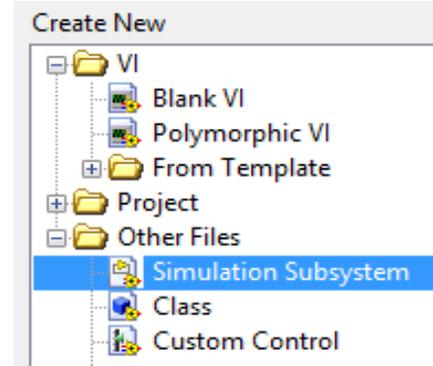
LabVIEW Example

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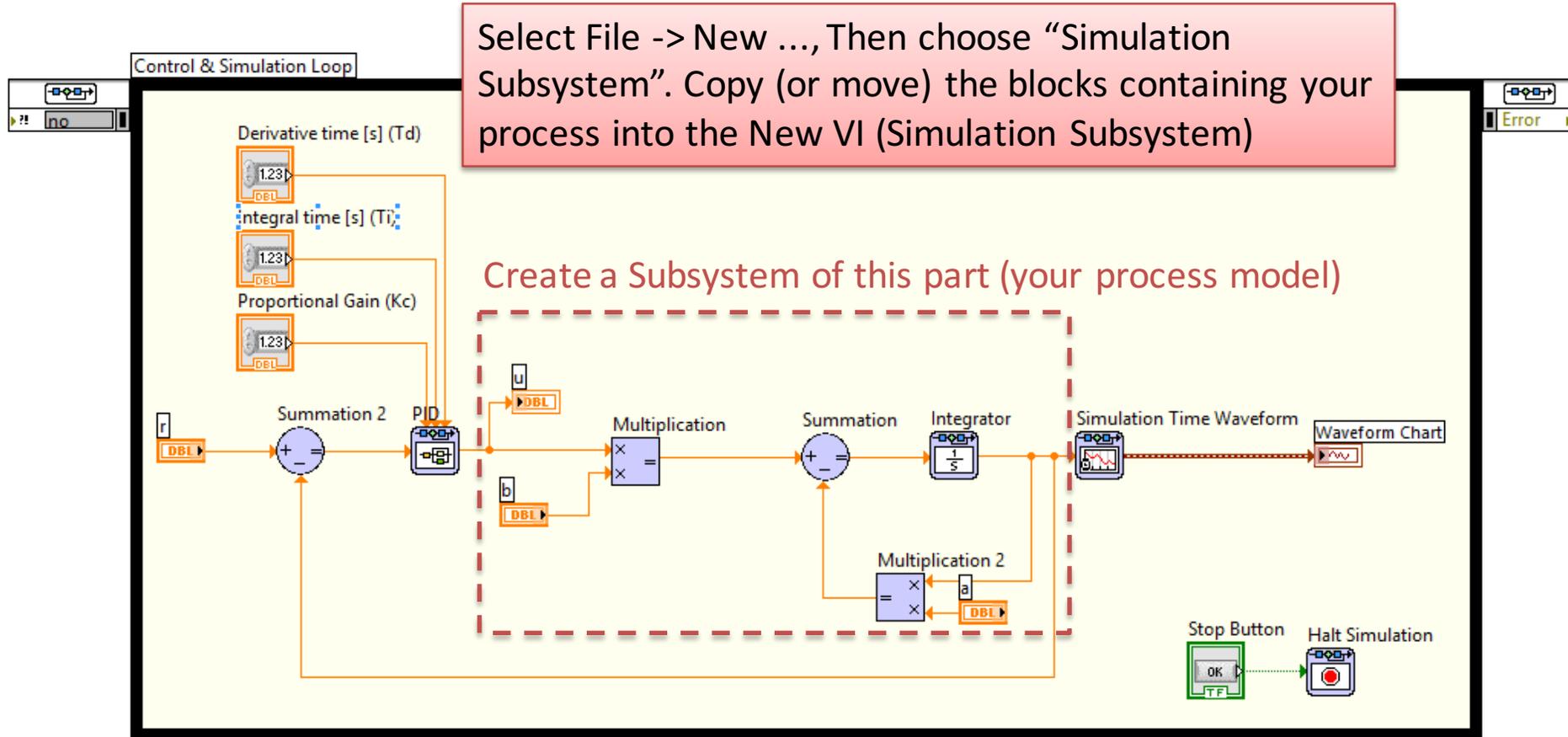
Simulation Subsystem

A Way to structure your code, similar to SubVIs

This is the recommended way to do it! – You can easily reuse your Subsystems in different VIs and your code becomes more structured!

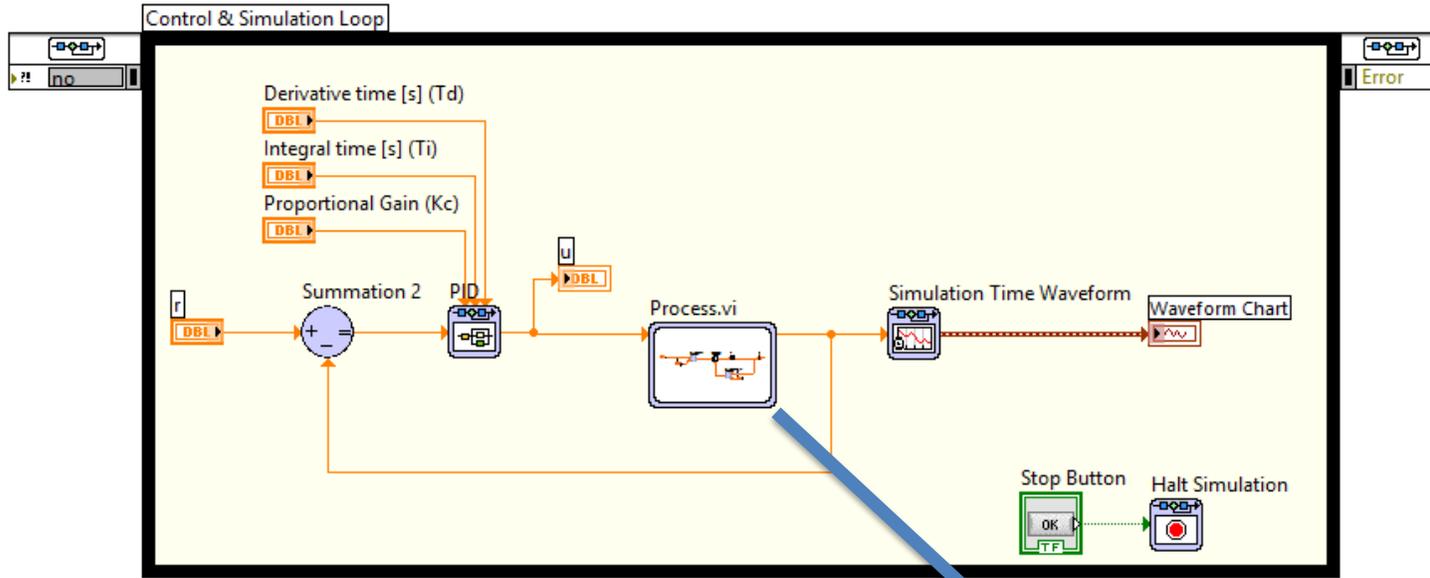


File -> New...

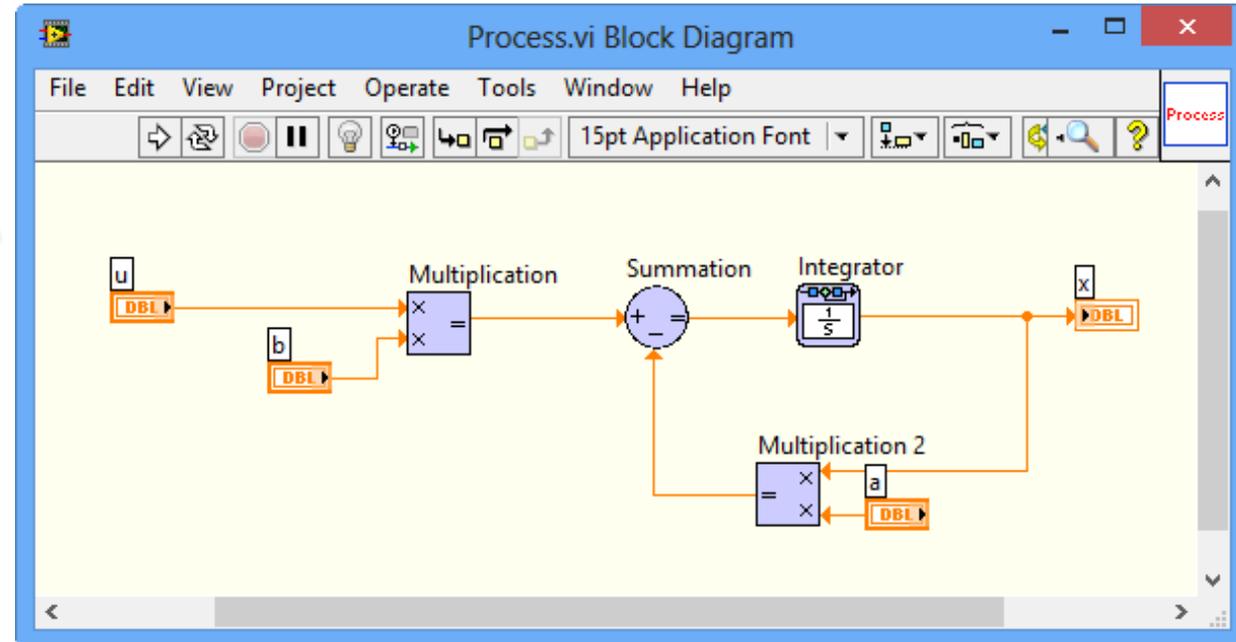
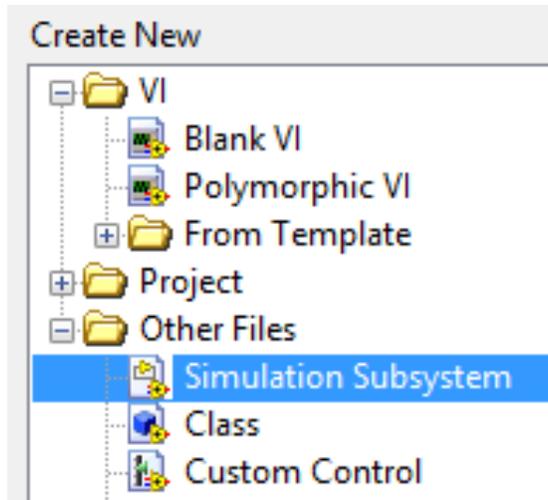


We will change your code above where you create a Simulation Sub System for your Process

Simulation Subsystem - Solutions

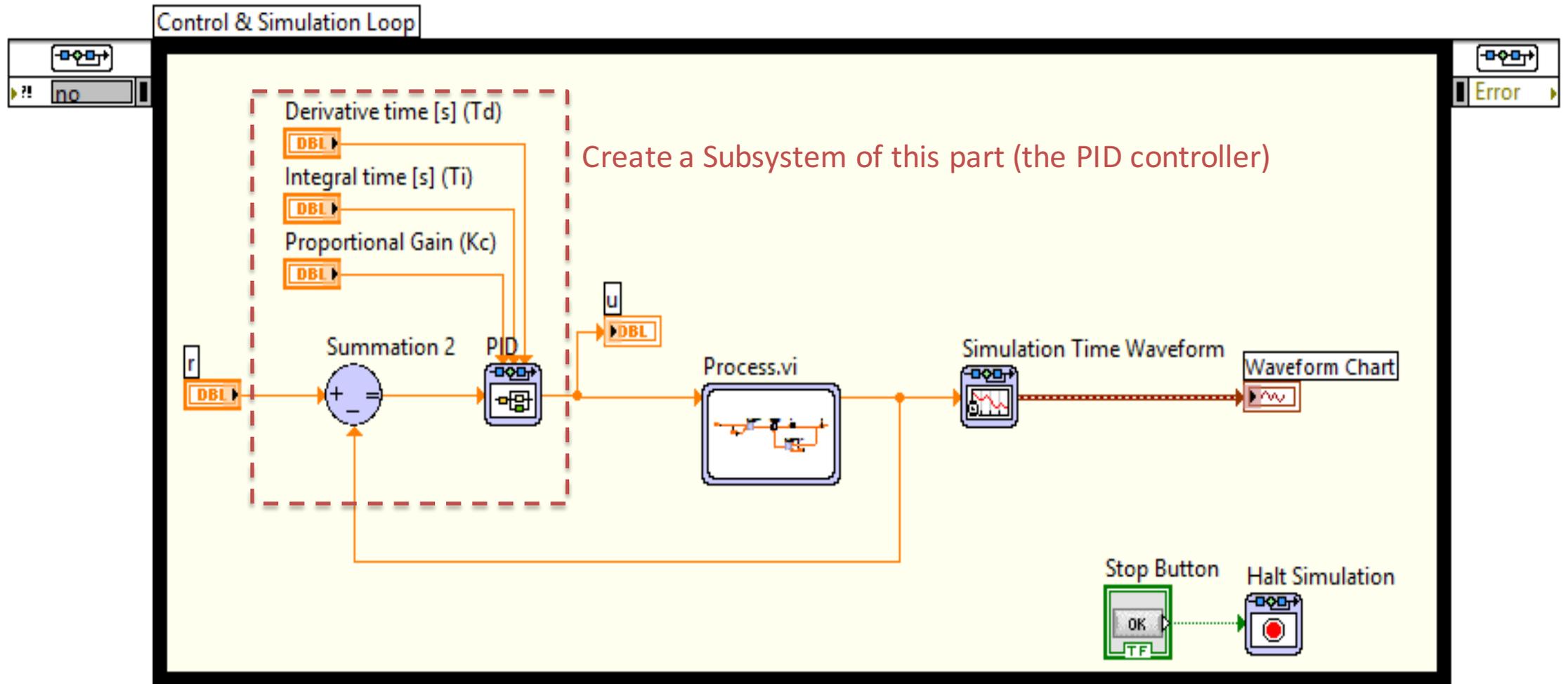


File -> New...



DEMO

Simulation Subsystem 2 (PID Controller)



Create a Subsystem of this part (the PID controller)



We will change your code above where you create a Simulation Sub System for the PID Controller as well.

DEMO



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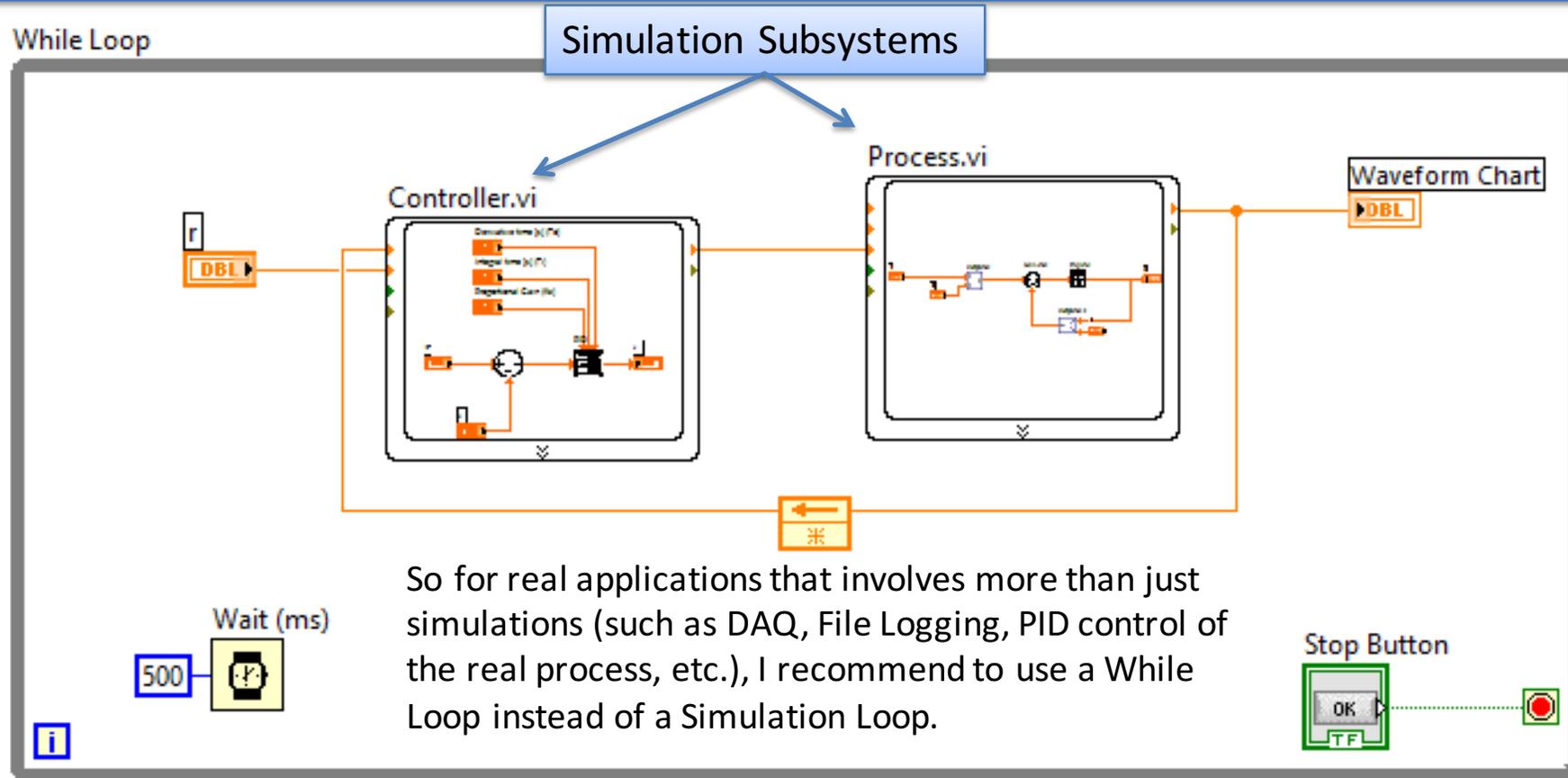
LabVIEW Example With While Loop

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Simulations using a While Loop



Note! The Simulation Loop has some drawbacks/is more complicated to use than an ordinary While Loop. If we use Simulation Subsystems, we can use them inside a While Loop instead! - which becomes very handy!



We will add the Controller and Process Subsystems inside a While loop as shown above

DEMO

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